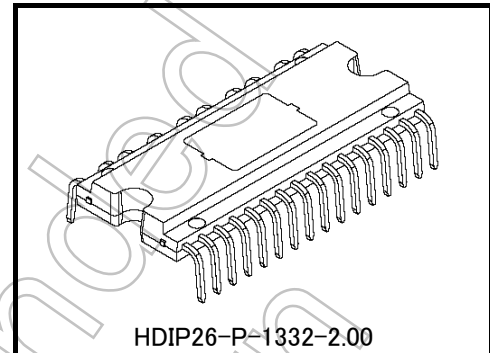


TOSHIBA Intelligent Power Device High Voltage Monolithic Silicon Power IC

# TPD4142K

The TPD4142K is a DC brushless motor driver using high-voltage PWM control. It is fabricated using a high-voltage SOI process. The device contains PWM circuit, 3-phase decode circuit, level shift high-side driver, low-side driver, IGBT outputs, FRDs, over-current and under-voltage protection circuits, and a thermal shutdown circuit. It is easy to control a DC brush less motor by applying a signal from a motor controller and a Hall amp/ Hall IC to the TPD4142K.



Weight: 3.8 g (typ.)

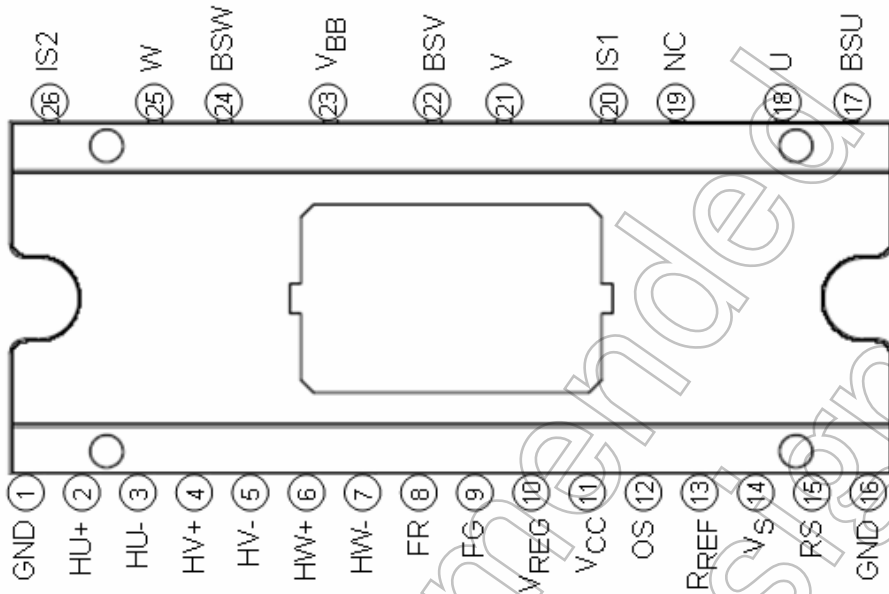
## Features

- High voltage power side and low voltage signal side terminal are separated.
- Bootstrap circuits give simple high-side supply.
- Bootstrap diodes are built in.
- PWM and 3-phase decode circuit are built in.
- Outputs Rotation pulse signals.
- 3-phase bridge output using IGBTs.
- FRDs are built in.
- Included over-current and under-voltage protection, and thermal shutdown.
- Package: 26-pin DIP.
- Compatible with Hall amp input and Hall IC input.

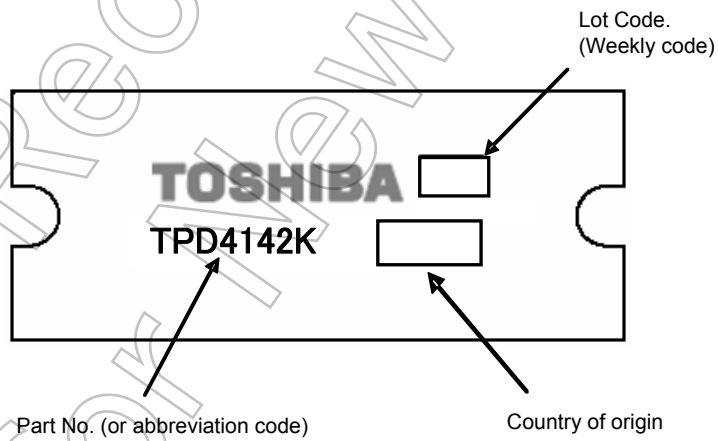
This product has a MOS structure and is sensitive to electrostatic discharge. When handling this product, ensure that the environment is protected against electrostatic discharge.

Start of commercial production  
2012-01

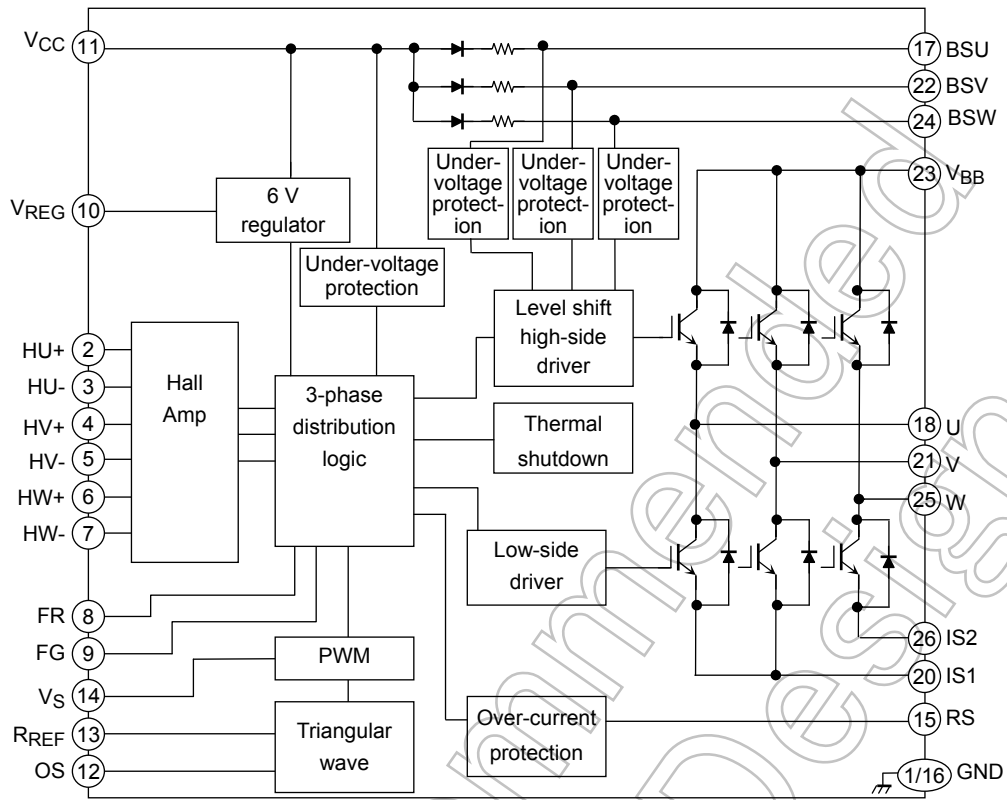
**Pin Assignment**



**Marking**



**Block Diagram**



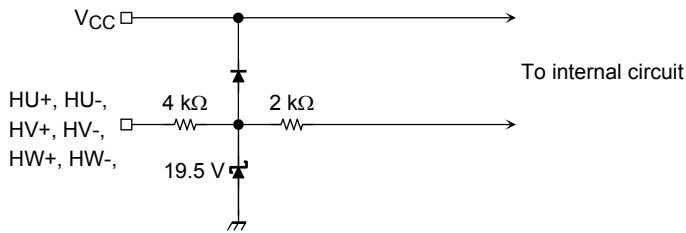
Not Recommended for New

**Pin Description**

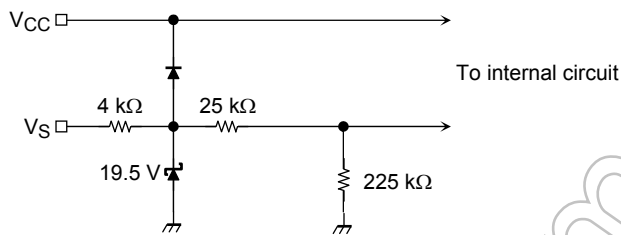
Pin No.	Symbol	Pin Description
1	GND	Ground pin.
2	HU+	U-phase Hall amp signal input pin. (Hall IC can be used.)
3	HU-	U-phase Hall amp signal input pin. (Hall IC can be used.)
4	HV+	V-phase Hall amp signal input pin. (Hall IC can be used.)
5	HV-	V-phase Hall amp signal input pin. (Hall IC can be used.)
6	HW+	W-phase Hall amp signal input pin. (Hall IC can be used.)
7	HW-	W-phase Hall amp signal input pin. (Hall IC can be used.)
8	FR	Forward/Reverse selection pin.
9	FG	Rotation pulse output pin.
10	VREG	6 V regulator output pin.
11	VCC	Control power supply pin.
12	OS	PWM triangular wave oscillation frequency setup pin. (Connect a capacitor to this pin.)
13	RREF	PWM triangular wave oscillation frequency setup pin. (Connect a resistor to this pin.)
14	VS	Speed control signal input pin. (PWM reference voltage input pin.)
15	RS	Over current detection pin.
16	GND	Ground pin.
17	BSU	U-phase bootstrap capacitor connecting pin.
18	U	U-phase output pin.
19	NC	Unused pin, which is not connected to the chip internally.
20	IS1	IGBT emitter/FRD anode pin.
21	V	V-phase output pin.
22	BSV	V-phase bootstrap capacitor connecting pin.
23	VBB	High-voltage power supply input pin.
24	BSW	W-phase bootstrap capacitor connecting pin.
25	W	W-phase output pin.
26	IS2	IGBT emitter/FRD anode pin.

**Internal circuit diagrams**

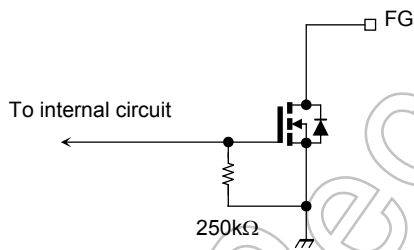
**Internal circuit diagram of HU+, HU-, HV+, HV-, HW+, HW- input pins**



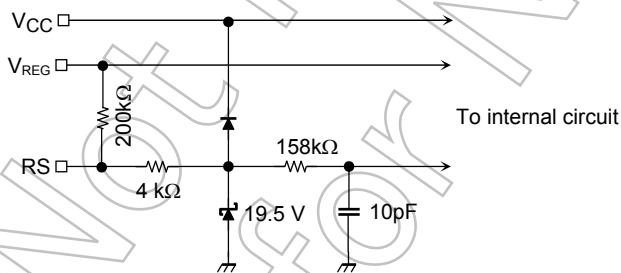
**Internal circuit diagram of Vs pin**



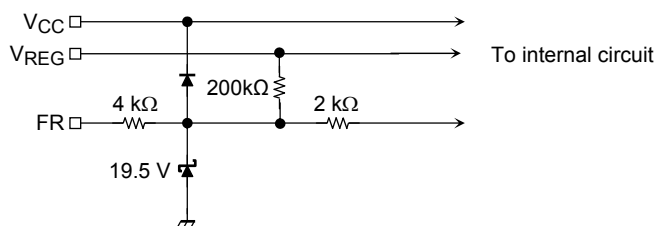
**Internal circuit diagram of FG pin**



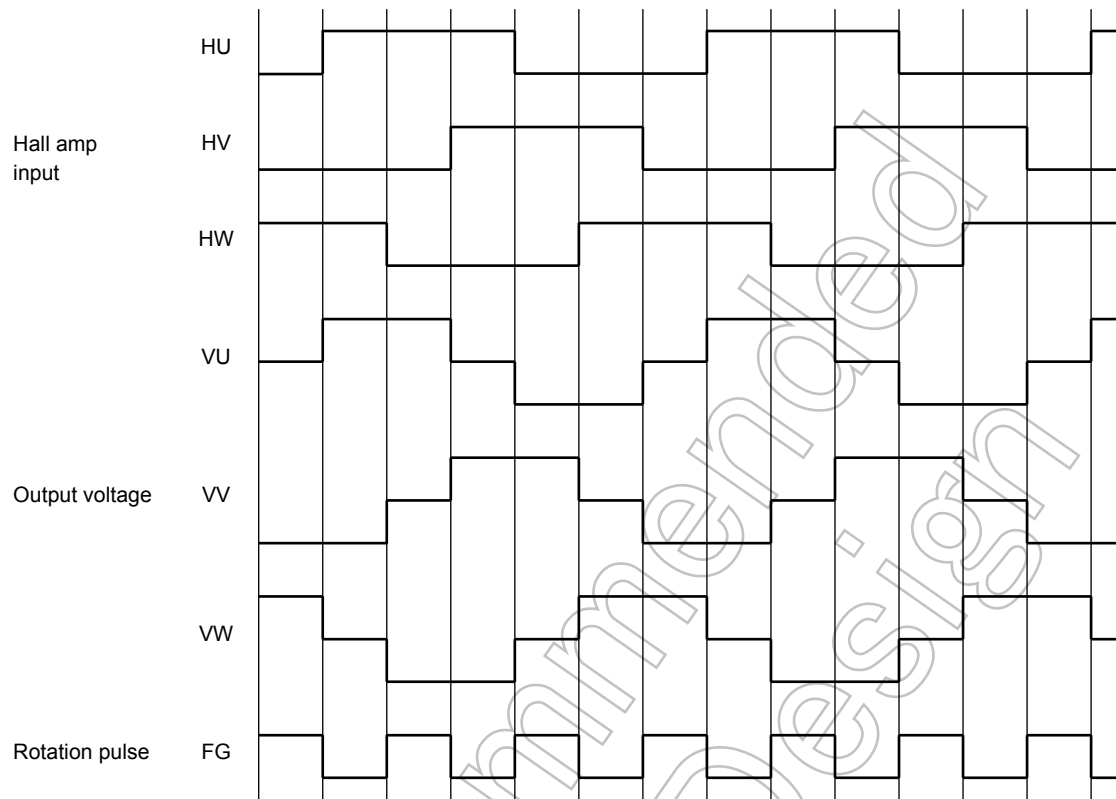
**Internal circuit diagram of RS pin**



**Internal circuit diagram of FR pin**



## Timing Chart



Note: Hall amp input logic high (H) refers to H\*+>H\*-. (\*: U/V/W)

## Truth Table

FR	Hall amp Input			U Phase		V Phase		W Phase		FG
	HU	HV	HW	High side	Low side	High side	Low side	High side	Low side	
H	H	L	H	ON	OFF	OFF	ON	OFF	OFF	L
H	H	L	L	ON	OFF	OFF	OFF	OFF	ON	H
H	H	H	L	OFF	OFF	ON	OFF	OFF	ON	L
H	L	H	L	OFF	ON	ON	OFF	OFF	OFF	H
H	L	H	H	OFF	ON	OFF	OFF	ON	OFF	L
H	L	L	H	OFF	OFF	OFF	ON	ON	OFF	H
H	L	L	L	OFF	OFF	OFF	OFF	OFF	OFF	L
H	H	H	H	OFF	OFF	OFF	OFF	OFF	OFF	L
L	H	L	H	OFF	ON	ON	OFF	OFF	OFF	H
L	H	L	L	OFF	ON	OFF	OFF	ON	OFF	L
L	H	H	L	OFF	OFF	OFF	ON	ON	OFF	H
L	L	H	L	ON	OFF	OFF	ON	OFF	OFF	L
L	L	H	H	ON	OFF	OFF	OFF	OFF	ON	H
L	L	L	H	OFF	OFF	ON	OFF	OFF	ON	L
L	L	L	L	OFF	OFF	OFF	OFF	OFF	OFF	L
L	H	H	H	OFF	OFF	OFF	OFF	OFF	OFF	L

Note: Hall amp input logic high (H) refers to H\*+>H\*-. (\*: U/V/W)

## Absolute Maximum Ratings (Ta = 25°C)

Characteristics	Symbol	Rating	Unit
Power supply voltage	V <sub>BB</sub>	500	V
	V <sub>CC</sub>	20	V
Output current (DC)	I <sub>out</sub>	1	A
Output current (pulse)	I <sub>outp</sub>	2	A
Input voltage (except V <sub>S</sub> )	V <sub>IN</sub>	-0.5 to V <sub>REG</sub> + 0.5	V
Input voltage (only V <sub>S</sub> )	V <sub>S</sub>	8.2	V
V <sub>REG</sub> current	I <sub>REG</sub>	50	mA
FG voltage	V <sub>FG</sub>	20	V
FG current	I <sub>FG</sub>	20	mA
Power dissipation (T <sub>c</sub> = 25°C)	P <sub>C</sub>	23	W
Operating junction temperature	T <sub>jopr</sub>	-40 to 135	°C
Junction temperature	T <sub>j</sub>	150	°C
Storage temperature	T <sub>stg</sub>	-55 to 150	°C

Note: Using continuously under heavy loads (e.g. the application of high temperature/current/voltage and the significant change in temperature, etc.) may cause this product to decrease in the reliability significantly even if the operating conditions (i.e. operating temperature/current/voltage, etc.) are within the absolute maximum ratings and the operating ranges.

Please design the appropriate reliability upon reviewing the Toshiba Semiconductor Reliability Handbook ("Handling Precautions"/"Derating Concept and Methods") and individual reliability data (i.e. reliability test report and estimated failure rate, etc).

## Electrical Characteristics (Ta = 25°C)

Characteristics	Symbol	Test Condition	Min	Typ.	Max	Unit
Operating power supply voltage	V <sub>BB</sub>	—	50	280	450	V
	V <sub>CC</sub>	—	13.5	15	17.5	
Current dissipation	I <sub>BB</sub>	V <sub>BB</sub> = 450 V Duty cycle = 0 %	—	—	0.5	mA
	I <sub>CC</sub>	V <sub>CC</sub> = 15 V Duty cycle = 0 %	—	2.0	10	
	I <sub>BS</sub> (ON)	V <sub>BS</sub> = 15 V, high side ON	—	190	470	μA
	I <sub>BS</sub> (OFF)	V <sub>BS</sub> = 15 V, high side OFF	—	180	415	
Hall amp input sensitivity	V <sub>HSENS</sub> (HA)	—	50	—	—	mV <sub>p-p</sub>
Hall amp input current	I <sub>HB</sub> (HA)	—	-2	0	2	μA
Hall amp common input voltage	CMV <sub>IN</sub> (HA)	—	0	—	8	V
Hall amp hysteresis width	ΔV <sub>IN</sub> (HA)	—	8	30	62	mV
Hall amp input voltage L→H	V <sub>LH</sub> (HA)	—	4	15	31	
Hall amp input voltage H→L	V <sub>HL</sub> (HA)	—	-31	-15	-4	
Output saturation voltage	V <sub>CEsatH</sub>	V <sub>CC</sub> = 15 V, I <sub>C</sub> = 0.5 A, high side	—	2.1	2.7	V
	V <sub>CEsatL</sub>	V <sub>CC</sub> = 15 V, I <sub>C</sub> = 0.5 A, low side	—	2.1	2.7	
FRD forward voltage	V <sub>FH</sub>	I <sub>F</sub> = 0.5 A, high side	—	1.7	2.2	V
	V <sub>FL</sub>	I <sub>F</sub> = 0.5 A, low side	—	1.7	2.2	
BSD forward voltage	V <sub>F</sub> (BSD)	I <sub>F</sub> = 500 μA	—	0.8	1.2	V
PWM ON-duty cycle	PWMMIN	—	0	—	—	%
	PWMMAX	—	—	—	100	
PWM ON-duty cycle, 0 %	V <sub>VS0</sub> %	PWM = 0 %	1.7	2.1	2.5	V
PWM ON-duty cycle, 100 %	V <sub>VS100</sub> %	PWM = 100 %	4.9	5.4	6.1	V
PWM ON-duty voltage range	V <sub>VS</sub> W	V <sub>VS100</sub> % – V <sub>VS0</sub> %	2.8	3.3	3.8	V
Output all-OFF voltage	V <sub>VS</sub> OFF	Output all OFF	1.1	1.3	1.5	V
Regulator voltage	V <sub>REG</sub>	V <sub>CC</sub> = 15 V, I <sub>REG</sub> = 30 mA	5	6	7	V
Speed control voltage range	V <sub>S</sub>	—	0	—	6.5	V
FG output saturation voltage	V <sub>FGsat</sub>	V <sub>CC</sub> = 15 V, I <sub>FG</sub> = 5 mA	—	—	0.5	V
Current control voltage	V <sub>R</sub>	—	0.46	0.5	0.54	V
Current control delay time	Dt	—	—	4.5	6.5	μs
Thermal shutdown temperature	T <sub>SD</sub>	—	135	—	185	°C
Thermal shutdown hysteresis	ΔT <sub>SD</sub>	—	—	50	—	°C
V <sub>CC</sub> under-voltage protection	V <sub>CC</sub> UVD	—	10	11	12	V
V <sub>CC</sub> under-voltage protection recovery	V <sub>CC</sub> UVR	—	10.5	11.5	12.5	V
V <sub>BS</sub> under-voltage protection	V <sub>BS</sub> UVD	—	9	10	11	V
V <sub>BS</sub> under-voltage protection recovery	V <sub>BS</sub> UVR	—	9.5	10.5	11.5	V
Refresh operating ON voltage	T <sub>R</sub> FO <sub>N</sub>	Refresh operation ON	1.1	1.3	1.5	V
Refresh operating OFF voltage	T <sub>R</sub> FO <sub>FF</sub>	Refresh operation OFF	3.1	3.8	4.6	V
Triangular wave frequency	f <sub>c</sub>	R = 27 kΩ, C = 1000 pF	16.5	20	25	kHz
Output-on delay time	t <sub>on</sub>	V <sub>BB</sub> = 280 V, V <sub>CC</sub> = 15 V, I <sub>C</sub> = 0.5 A	—	2.5	3.5	μs
Output-off delay time	t <sub>off</sub>	V <sub>BB</sub> = 280 V, V <sub>CC</sub> = 15 V, I <sub>C</sub> = 0.5 A	—	1.9	3	μs
FRD reverse recovery time	t <sub>rr</sub>	V <sub>BB</sub> = 280 V, V <sub>CC</sub> = 15 V, I <sub>C</sub> = 0.5 A	—	150	—	ns





## External Parts

Typical external parts are shown in the following table.

Part	Typical	Purpose	Remarks
C <sub>1</sub> , C <sub>2</sub> , C <sub>3</sub>	25 V/2.2 μF	Bootstrap capacitor	(Note 1)
R <sub>1</sub>	0.62 Ω ± 1 % (1 W)	Current detection	(Note 2)
C <sub>4</sub>	25 V/1000 pF ± 5 %	PWM frequency setup	(Note 3)
R <sub>2</sub>	27 kΩ ± 5 %	PWM frequency setup	(Note 3)
C <sub>5</sub>	25 V/10 μF	Control power supply stability	(Note 4)
C <sub>6</sub>	25 V/0.1 μF	V <sub>REG</sub> power supply stability	(Note 4)
R <sub>3</sub>	5.1 kΩ	FG pin pull-up resistor	(Note 5)

Note 1: The required bootstrap capacitance value varies according to the motor drive conditions. Although the IC can operate at above the V<sub>BS</sub> undervoltage level, it is however recommended that the capacitor voltage be greater than or equal to 13.5 V to keep the power dissipation small. The capacitor is biased by V<sub>CC</sub> and must be sufficiently derated accordingly.

Note 2: The following formula shows the detection current:  $I_O = V_R / R_1$  (V<sub>R</sub> = 0.5 V typ.)  
Do not exceed a detection current of 1 A when using the IC.

Note 3: With the combination of C<sub>4</sub> and R<sub>2</sub> shown in the table, the PWM frequency is around 20 kHz. The IC intrinsic error factor is around 10 %.

The PWM frequency is broadly expressed by the following formula. (In this case, the stray capacitance of the printed circuit board needs to be considered.)

$$f_c = 0.65 \div \{ C_4 \times (R_2 + 4.25 \text{ k}\Omega) \} \quad [\text{Hz}]$$

R<sub>2</sub> creates the reference current of the PWM triangular wave charge/discharge circuit. If R<sub>2</sub> is set too small it exceeds the current capacity of the IC internal circuits and the triangular wave distorts. Set R<sub>2</sub> to at least 9 kΩ.

Note 4: When using the IC, adjustment is required in accordance with the use environment. When mounting, place as close to the base of the IC leads as possible to improve noise elimination.

Note 5: The FG pin is open drain. If the FG pin is not used, connect to the GND.

Note 6: If noise is detected on the Input signal pin, add a capacitor between inputs.

Note 7: A Hall device should use an indium antimony system. It recommend that the peak Hall device voltage should set more than 300mV.

## Handling precautions

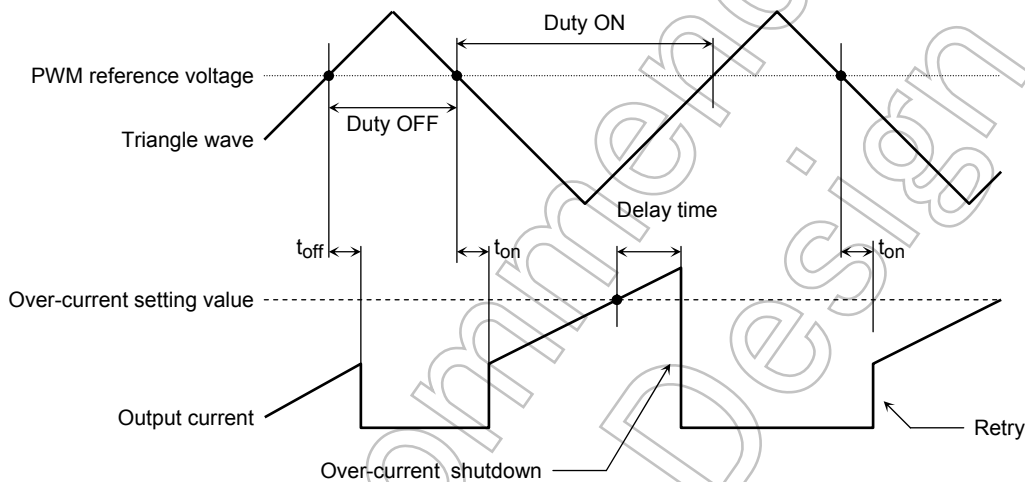
- When switching the power supply to the circuit on/off, ensure that V<sub>S</sub> < V<sub>VSOFF</sub> (all IGBT outputs off). At that time, either the V<sub>CC</sub> or the V<sub>BB</sub> can be turned on/off first. Note that if the power supply is switched off as described above, the IC may be destroyed if the current regeneration route to the V<sub>BB</sub> power supply is blocked when the V<sub>BB</sub> line is disconnected by a relay or similar while the motor is still running.
- The IC has a forward/reverse rotation control pin (FR). To change the rotation direction, switch the FR pin after the motor is stopped in the state that the V<sub>S</sub> voltage is lower than or equal to 1.1 V. When the FR pin is switched while the motor is rotating, the following malfunctions may occur.  
A shoot-through current may flow between the upper arm and lower arm in the output stage (IGBT) at that moment when the motor is switched.  
An over current may flow into the area where the over current protection circuit cannot detect it.
- The triangular wave oscillator circuit, with externally connected C<sub>4</sub> and R<sub>2</sub>, charges and discharges minute amounts of current. Therefore, subjecting the IC to noise when mounting it on the board may distort the triangular wave or cause malfunction. To avoid this, attach external parts to the base of the IC leads or isolate them from any tracks or wiring which carries large current.
- The PWM of this IC is controlled by the on/off state of the high-side IGBT.
- If a motor is locked where V<sub>BB</sub> voltage is low and duty is 100 %, it may not be possible to reboot after the load is released as a result of the high side being ON immediately prior to the motor being locked. This is because, over time, the bootstrap voltage falls, the high-side voltage decrease protection operates and the high-side output becomes OFF. In this case, since the level shift pulse necessary to turn the high side ON cannot be generated, reboot is not possible. A level shift pulse is generated by either the edge of a Hall sensor output or the edge of an internal PWM signal, but neither edge is

available due to the motor lock and duty 100 % command. In order to reboot after a lock, the high-side power voltage must return to a level 0.5 V (typ.) higher than the voltage decrease protection level, and a high-side input signal must be introduced. As a high-side input signal is created by the aforementioned level shift pulse, it is possible to reboot by reducing PWM duty to less than 100 % or by forcing the motor to turn externally and creating an edge at a Hall sensor output. In order to ensure reboot after a system lock, the motor specification must be such that maximum duty is less than 100 %.

## Description of Protection Function

### (1) Over-current protection

The IC incorporates an over-current protection circuit to protect itself against over current at startup or when a motor is locked. This protection function detects voltage generated in the current-detection resistor connected to the RS pin. When this voltage exceeds  $V_R$  ( $= 0.5$  V typ.), the high-side IGBT output, which is on, temporarily shuts down after a delay time, preventing any additional current from flowing to the IC. The next PWM ON signal releases the shutdown state.



### (2) Under-voltage protection

The IC incorporates under-voltage protection circuits to prevent the IGBT from operating in unsaturated mode when the VCC voltage or the VBS voltage drops.

When the VCC power supply falls to the IC internal setting  $V_{CCUVD}$  ( $= 11$  V typ.), all IGBT outputs shut down regardless of the input. This protection function has hysteresis. When the VCC power supply reaches 0.5 V higher than the shutdown voltage ( $V_{CCUVR}$  ( $= 11.5$  V typ.)), the IC is automatically restored and the IGBT is turned on/off again by the input.

When the VBS supply voltage drops  $V_{BSUVD}$  ( $= 10$  V typ.), the high-side IGBT output shuts down. When the VBS supply voltage reaches 0.5 V higher than the shutdown voltage ( $V_{BSUVR}$  ( $= 10.5$  V typ.)), the IGBT is turned on/off again by the input signal.

### (3) Thermal shutdown

The IC incorporates a thermal shutdown circuit to protect itself against excessive rise in temperature. When the temperature of this chip rises to the internal setting TSD due to external causes or internal heat generation, all IGBT outputs shut down regardless of the input. This protection function has hysteresis  $\Delta TSD$  ( $= 50$  °C typ.). When the chip temperature falls to  $TSD - \Delta TSD$ , the chip is automatically restored and the IGBT is turned on/off again by the input.

Because the chip contains just one temperature-detection location, when the chip heats up due to the IGBT for example, the distance between the detection location and the IGBT (the source of the heat) can cause differences in the time taken for shutdown to occur. Therefore, the temperature of the chip may rise higher than the initial thermal shutdown temperature.

**Description of Bootstrap Capacitor Charging and Its Capacitance**

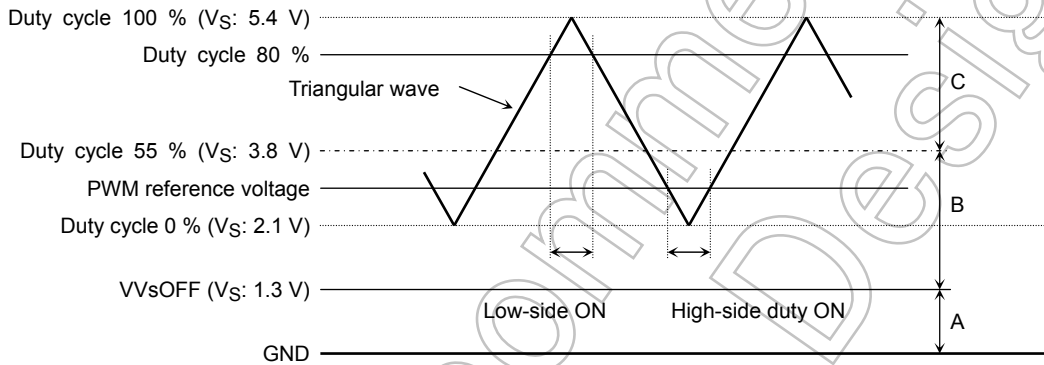
The IC uses bootstrapping for the power supply for high-side drivers. The bootstrap capacitor is charged by turning on the low-side IGBT of the same arm (approximately 1/5 of PWM cycle) while the high-side IGBT controlled by PWM is off. (For example, to drive at 20 kHz, it takes approximately 10 μs per cycle to charge the capacitor.) When the V<sub>S</sub> voltage exceeds 3.8 V (55 % duty), the low-side IGBT is continuously in the off state. This is because when the PWM on-duty becomes larger, the arm is short-circuited while the low-side IGBT is on. Even in this state, because PWM control is being performed on the high-side IGBT, the regenerative current of the diode flows to the low-side FRD of the same arm, and the bootstrap capacitor is charged. Note that when the on-duty is 100 %, diode regenerative current does not flow; thus, the bootstrap capacitor is not charged. When driving a motor at 100 % duty cycle, take the voltage drop at 100 % duty (see the figure below) into consideration to determine the capacitance of the bootstrap capacitor.

Capacitance of the bootstrap capacitor = Current dissipation (max) of the high-side driver × Maximum drive time / (V<sub>CC</sub> - V<sub>F</sub> (BSD) + V<sub>F</sub> (FRD) - 13.5) [F]

V<sub>F</sub> (BSD) : Bootstrap diode forward voltage

V<sub>F</sub> (FRD) : First recovery diode forward voltage

Consideration must be made for aging and temperature change of the capacitor.



V <sub>S</sub> Range	IGBT Operation
A	Both high and low-side OFF.
B	Charging range. Low-side IGBT refreshing on the phase the high-side IGBT in PWM.
C	No charging range. High-side at PWM according to the timing chart. Low-side no refreshing.

**Safe Operating Area**

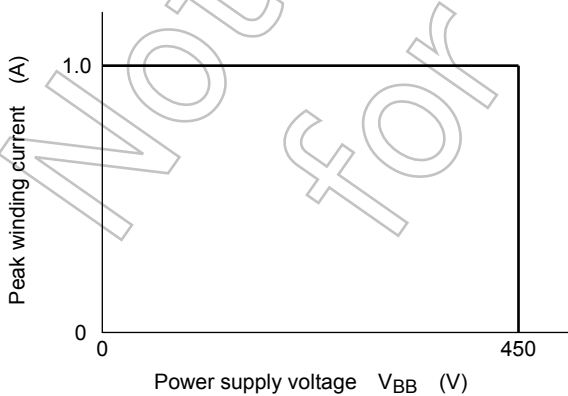
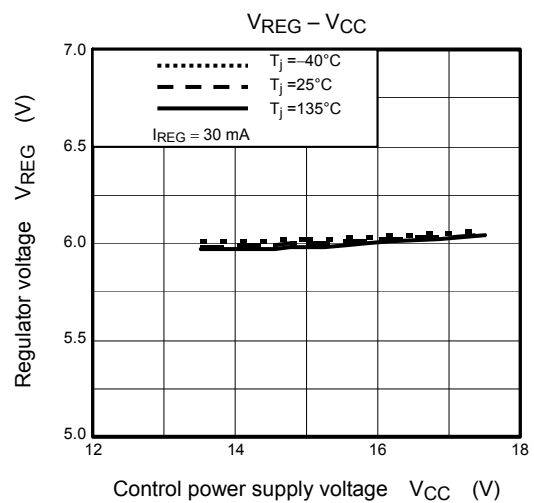
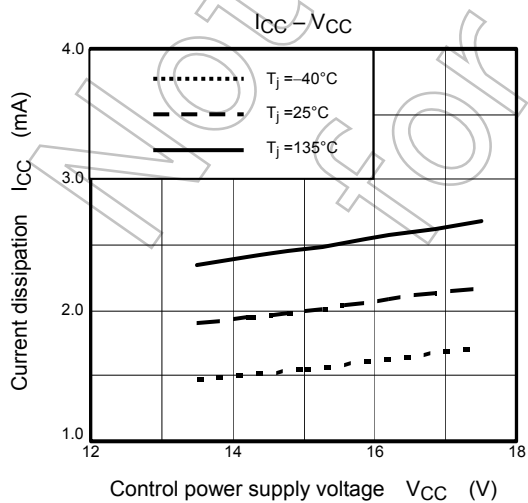
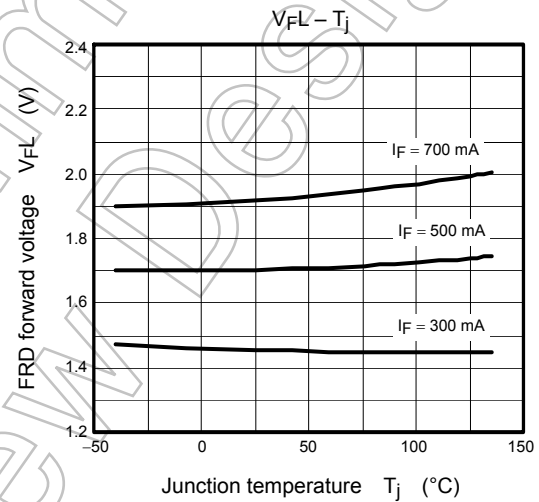
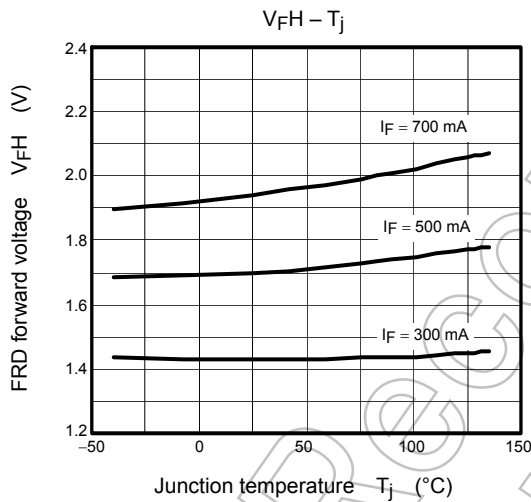
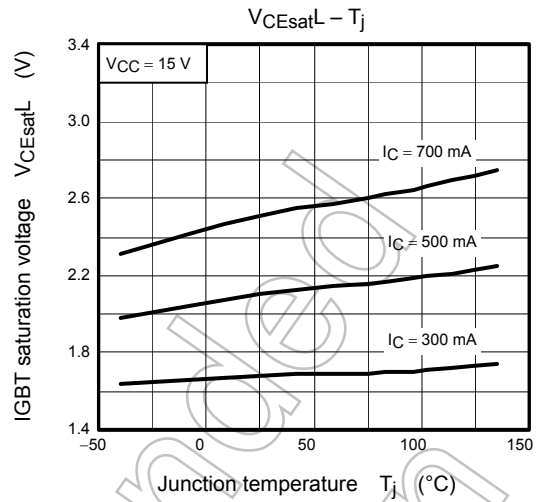
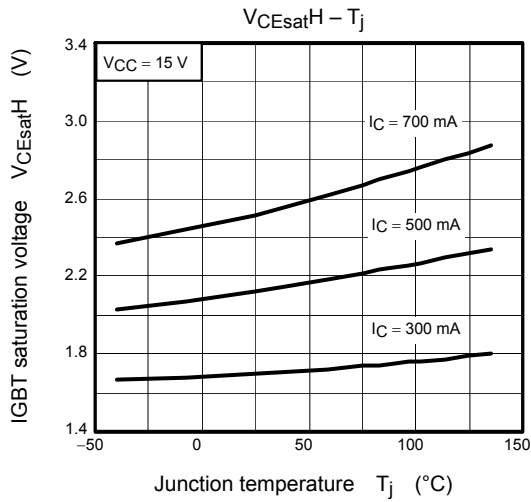
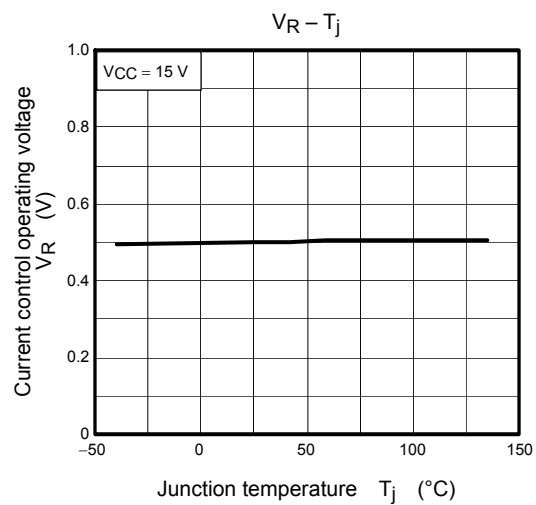
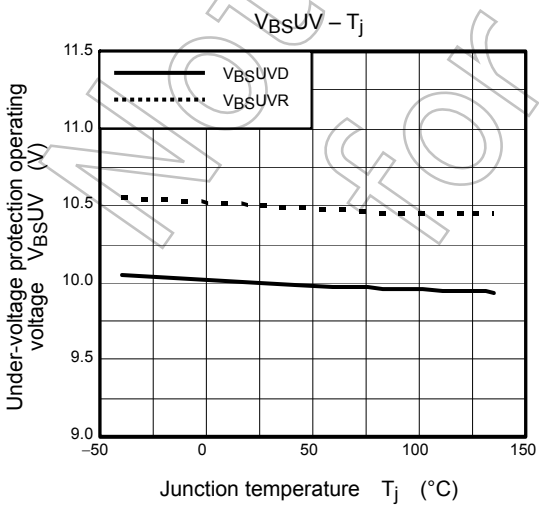
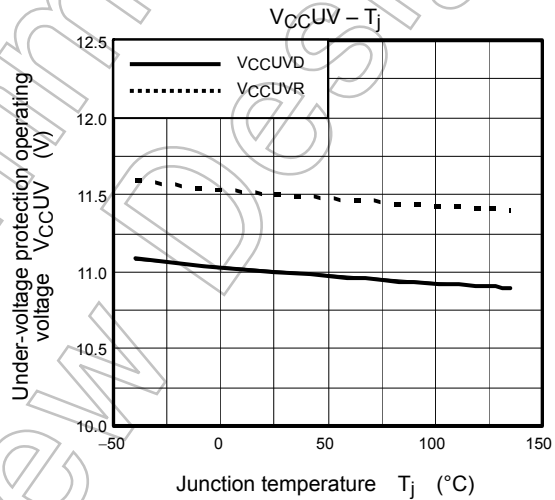
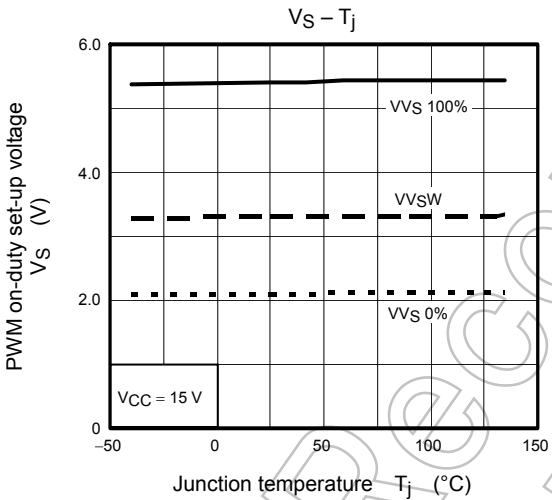
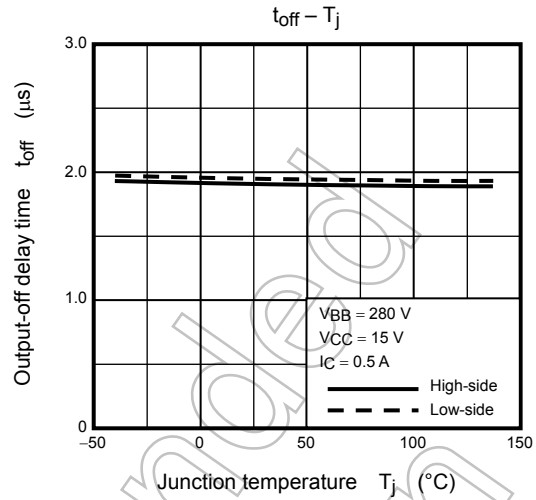
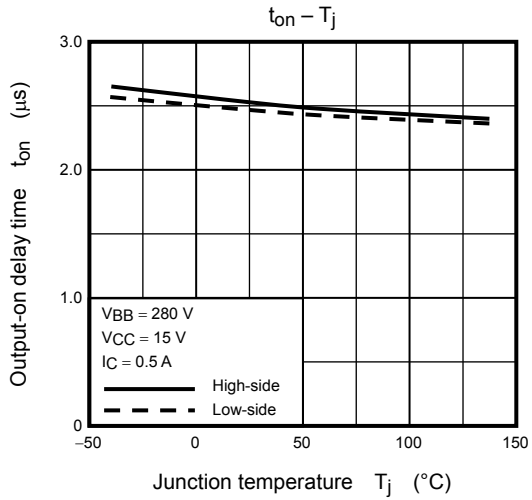
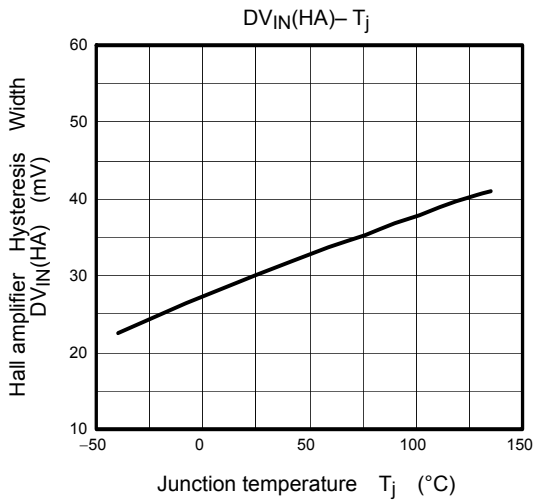
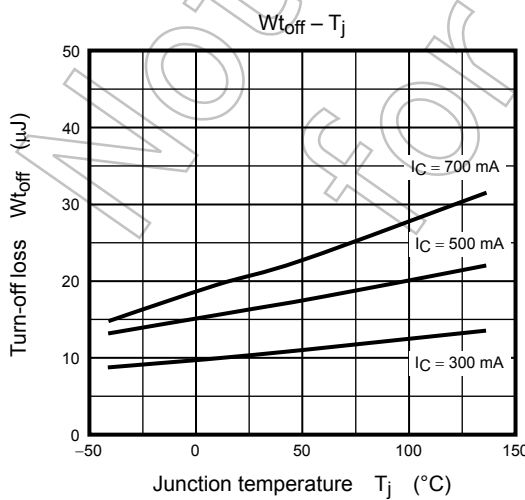
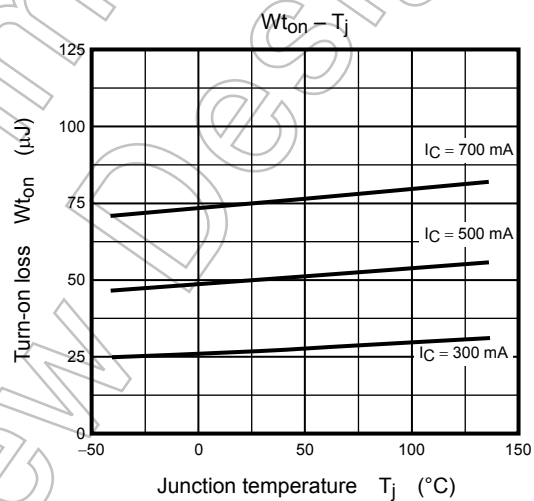
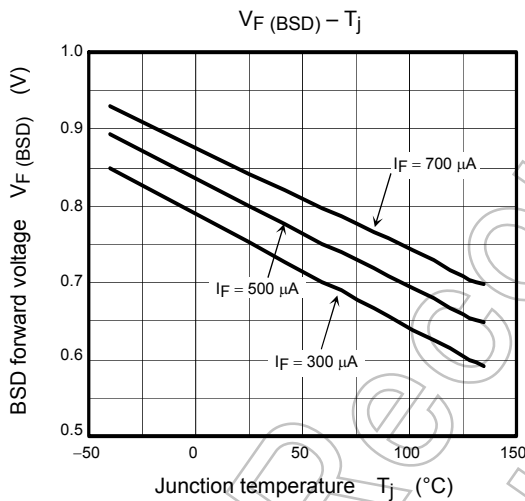
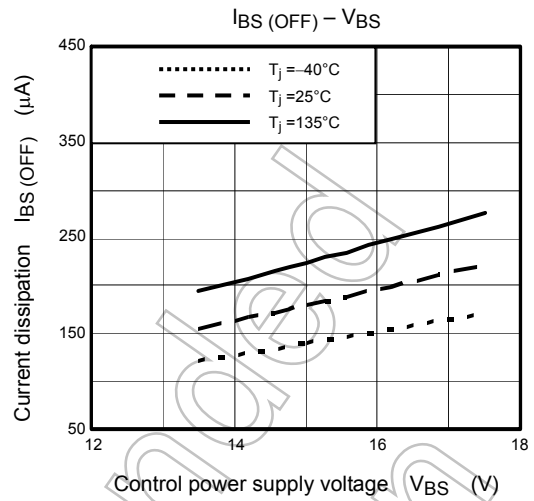
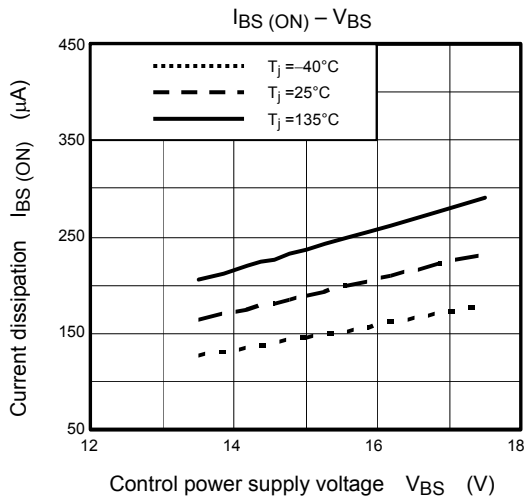


Figure 1 SOA at T<sub>j</sub> = 135°C

Note: The above safe operating areas are at T<sub>j</sub> = 135 °C (Figure 1).

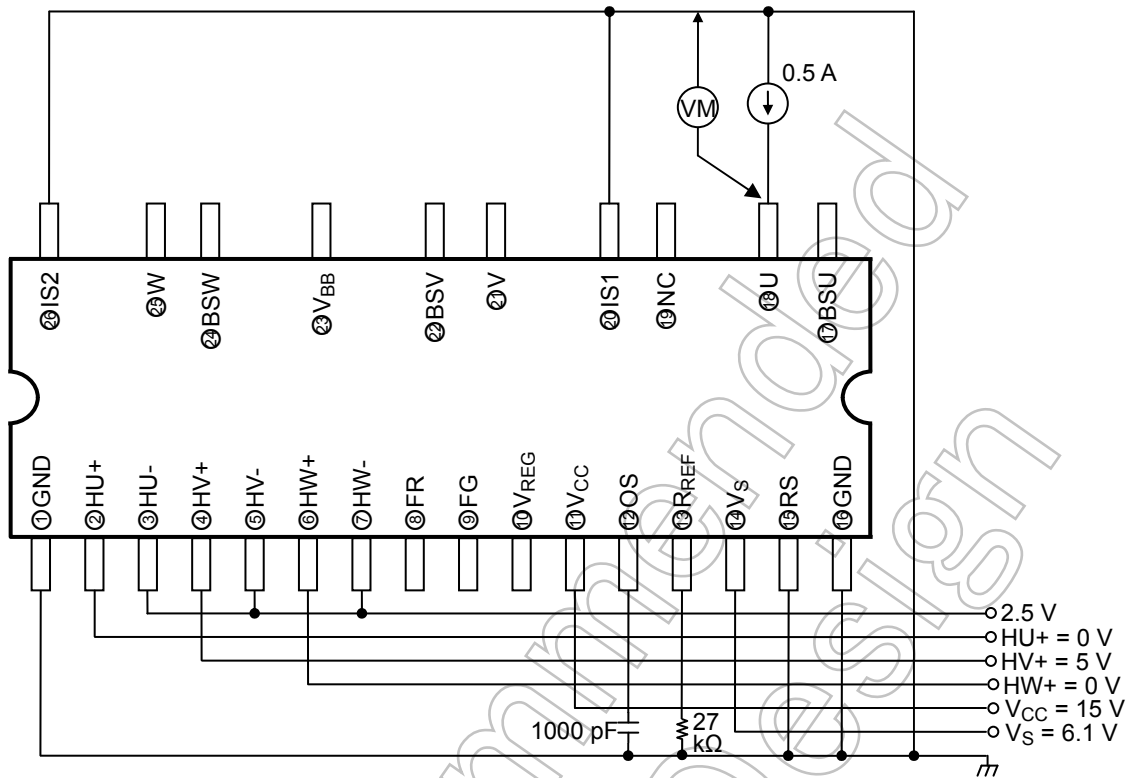




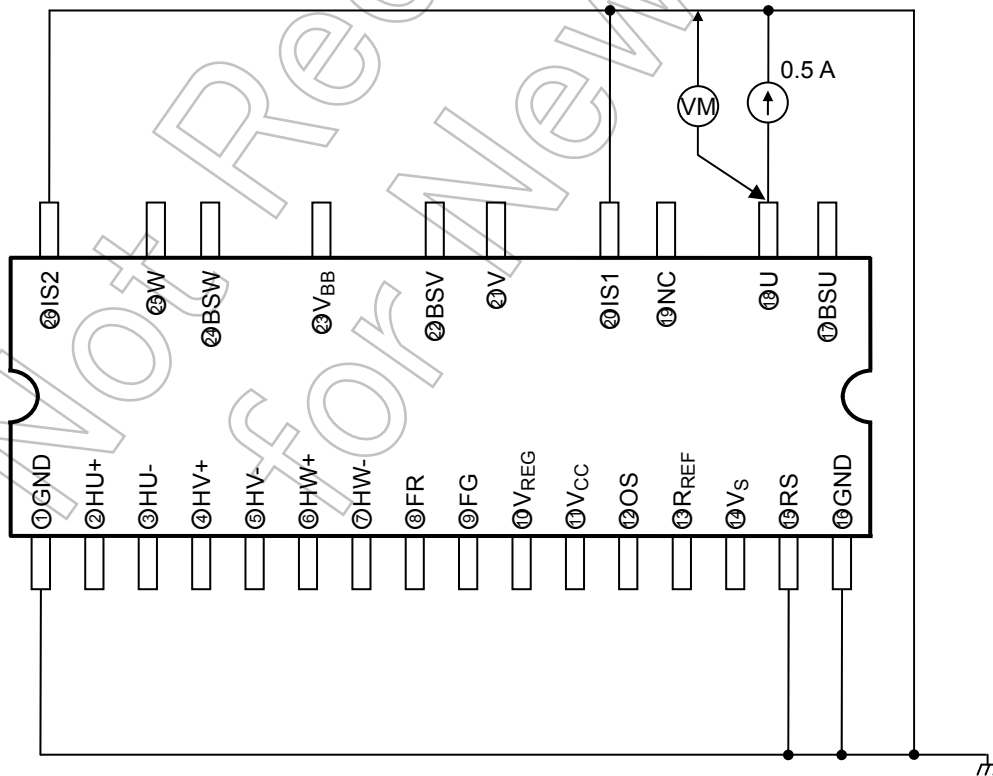


**Test Circuits**

**IGBT Saturation Voltage (U-phase low side)**

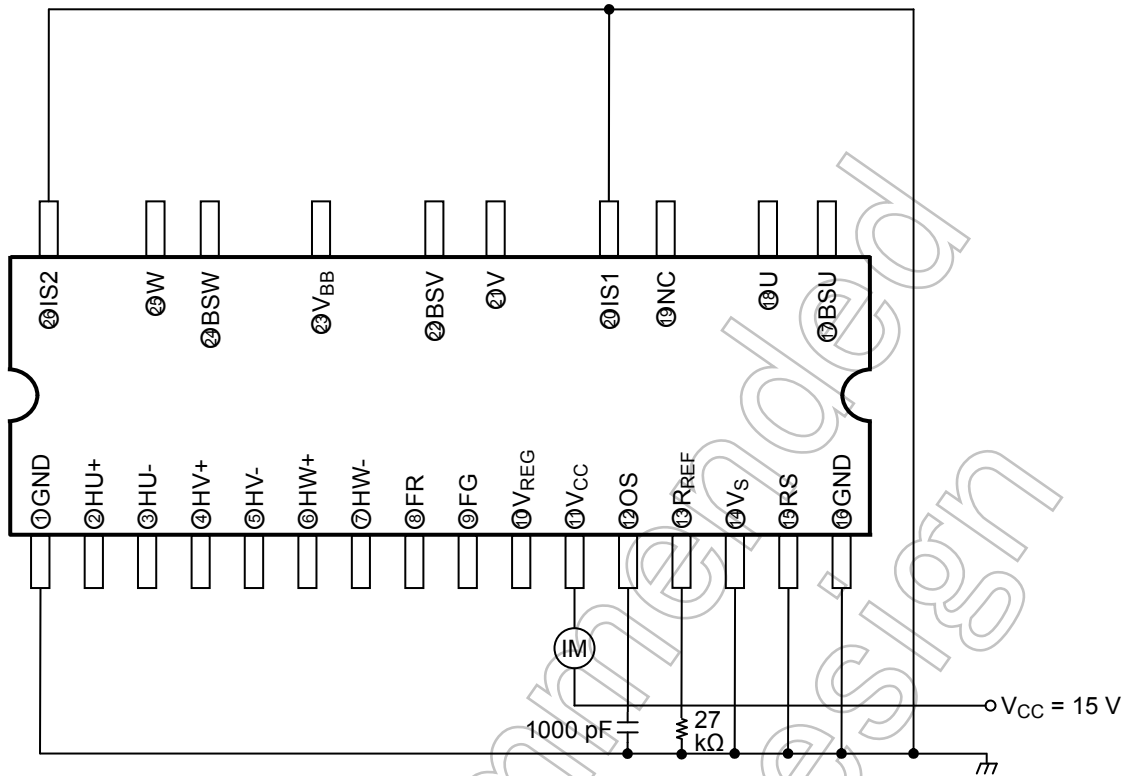


**FRD Forward Voltage (U-phase low side)**

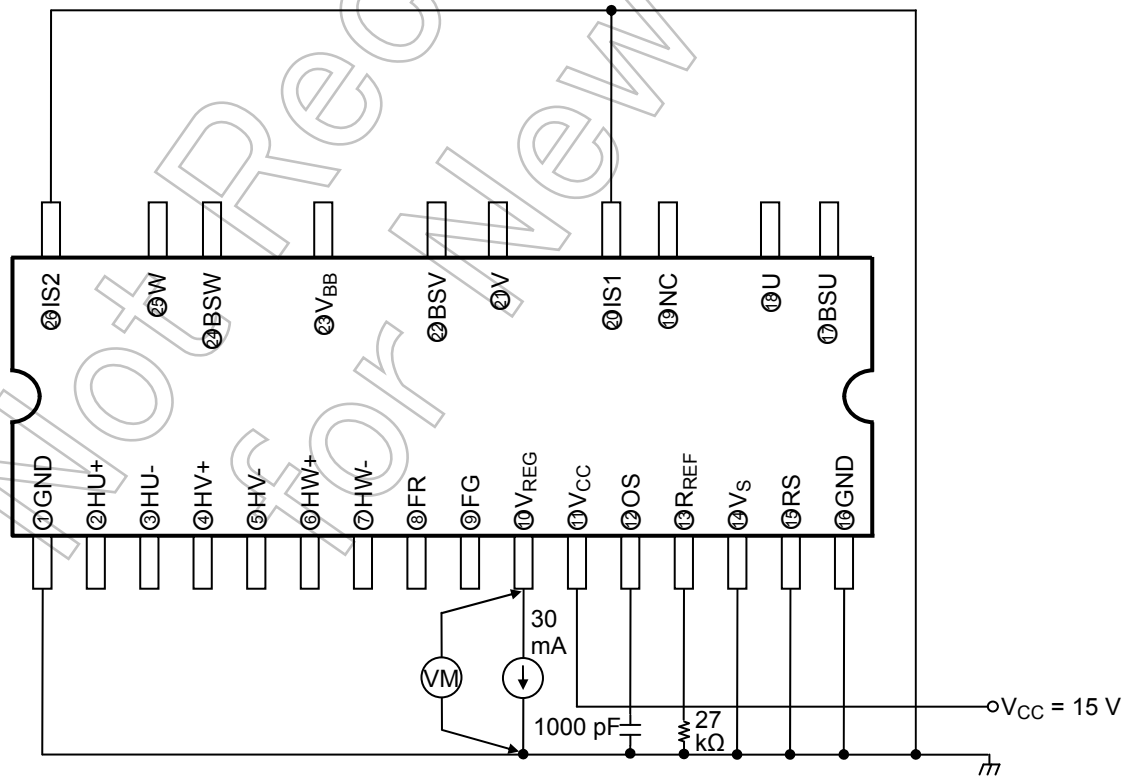




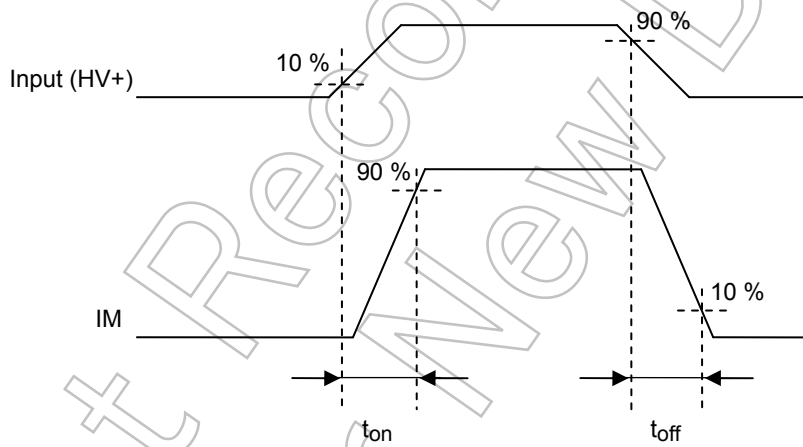
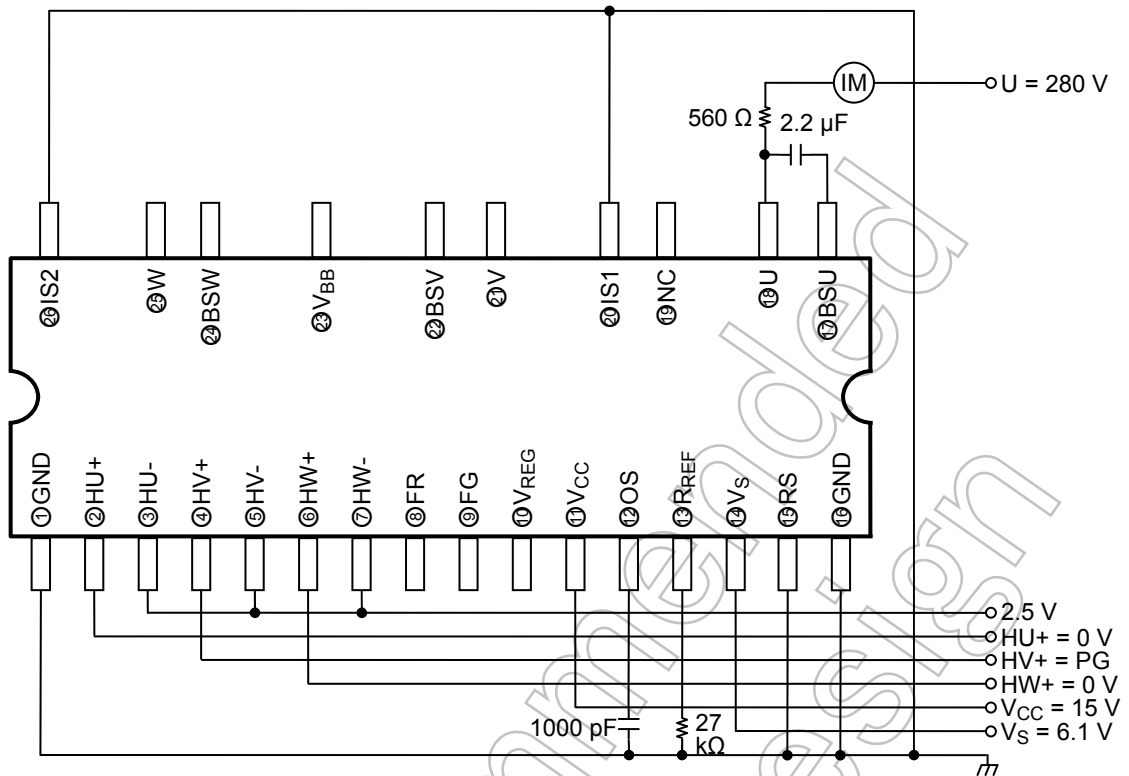
**V<sub>CC</sub> Current Dissipation**



**Regulator Voltage**



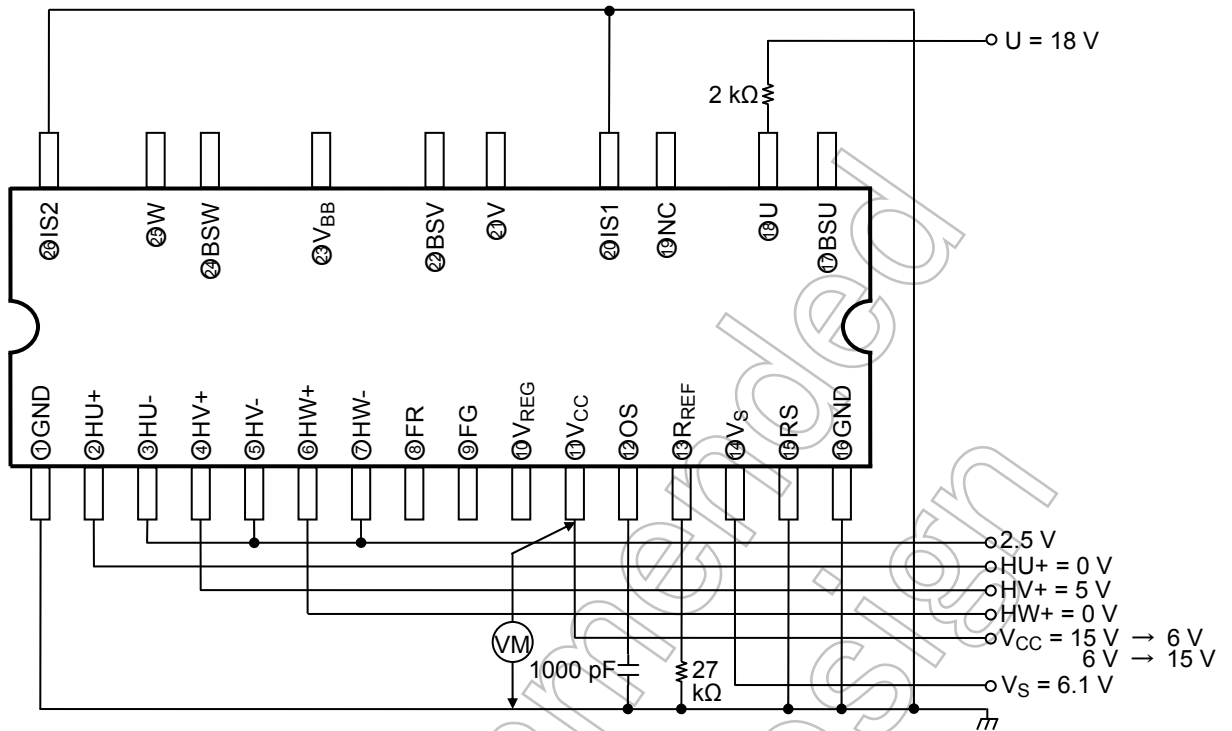
Output ON/OFF Delay Time (U-phase low side)



Not Recommended for New Design

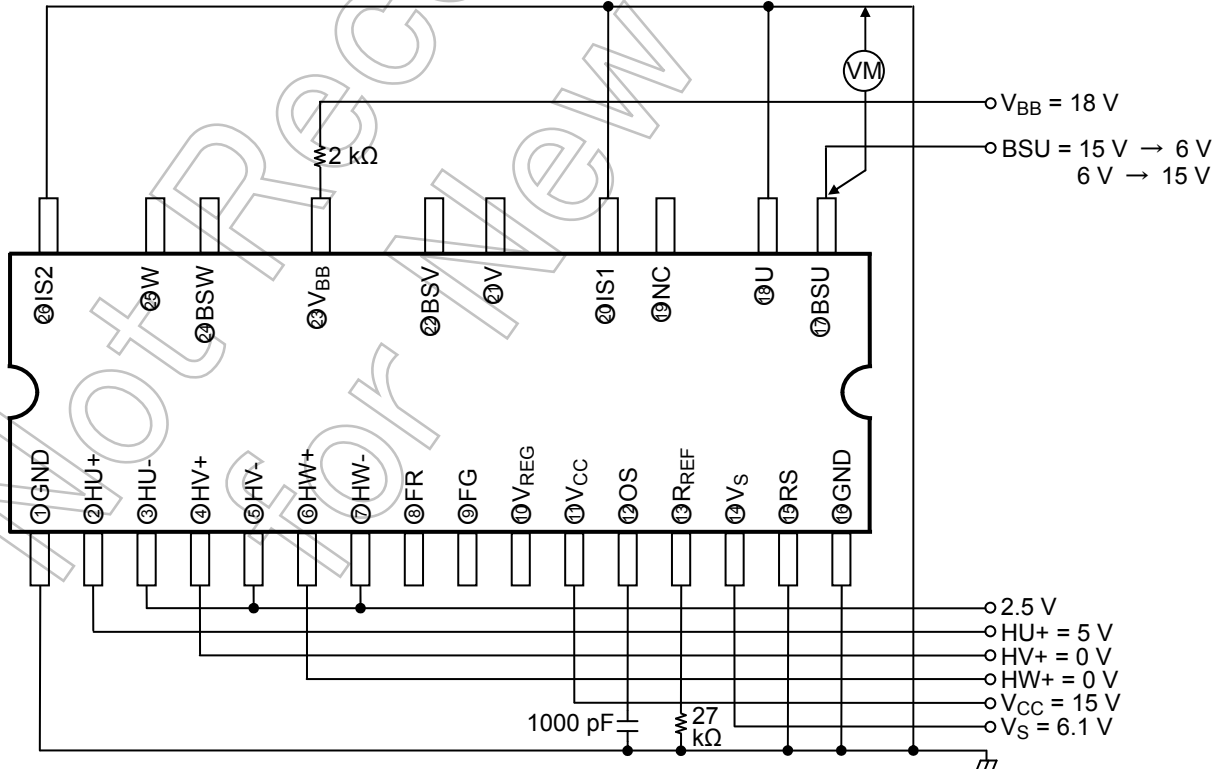


**V<sub>CC</sub> Under voltage Protection Operating/Recovery Voltage (U-phase low side)**



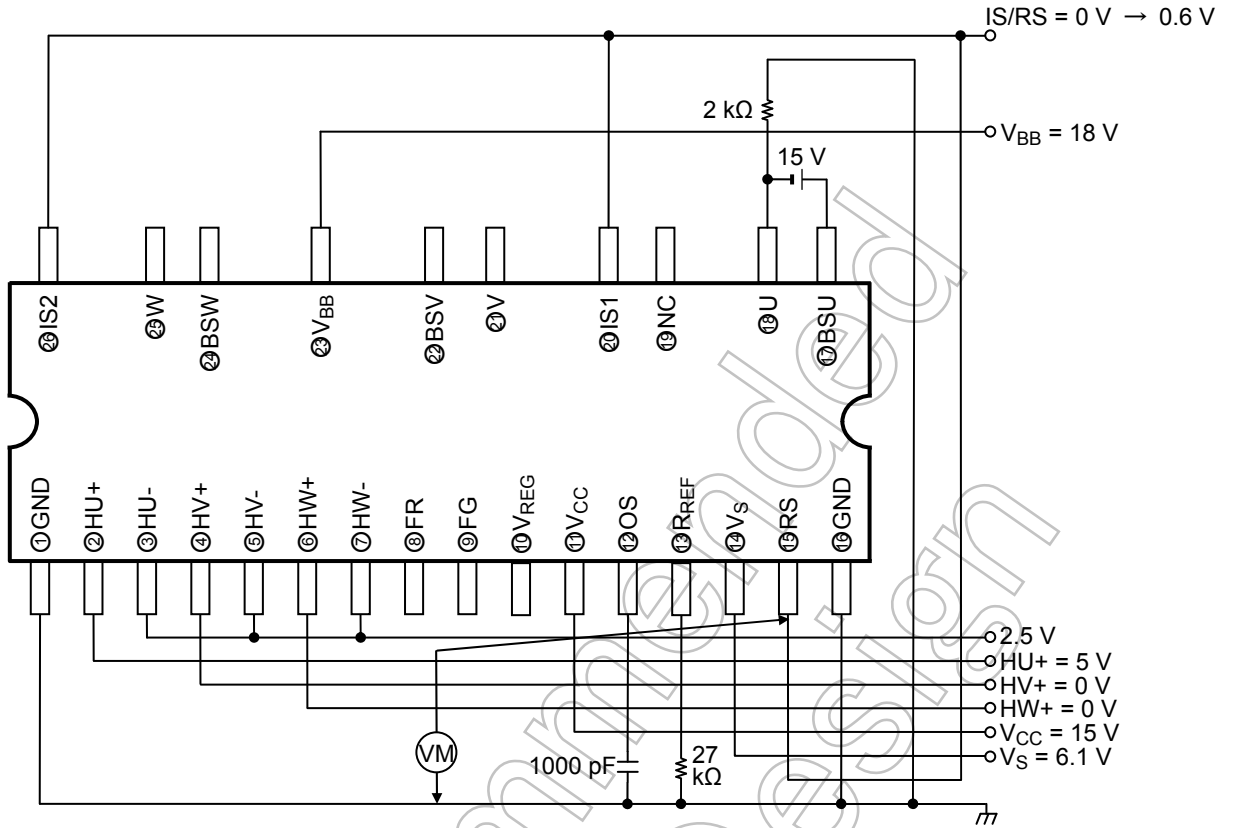
Note: Sweeps the V<sub>CC</sub> pin voltage from 15 V and monitors the U pin voltage.  
 The V<sub>CC</sub> pin voltage when output is off defines the under-voltage protection operating voltage.  
 Also sweeps from 6 V to increase. The V<sub>CC</sub> pin voltage when output is on defines the under voltage protection recovery voltage.

**V<sub>BS</sub> Under-voltage Protection Operating/Recovery Voltage (U-phase high side)**



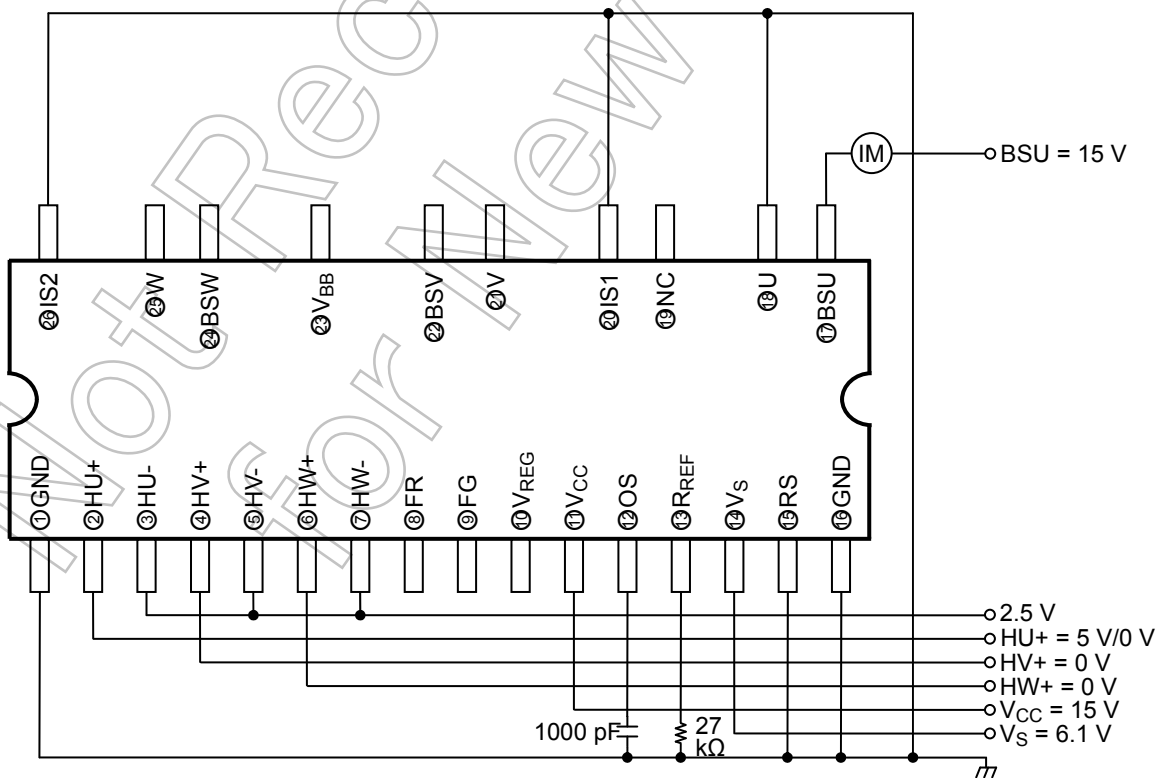
Note: Sweeps the BSU pin voltage from 15 V to decrease and monitors the V<sub>BB</sub> pin voltage. The BSU pin voltage when output is off defines the under voltage protection operating voltage. Also sweeps the BSU pin voltage from 6V to increase and change the HU pin voltage at 5V → 0V → 5V each time. It repeats similarly output is on. The BSU pin voltage when output is on defines the under voltage protection recovery voltage.

**Current Control Operating Voltage (U-phase high side)**

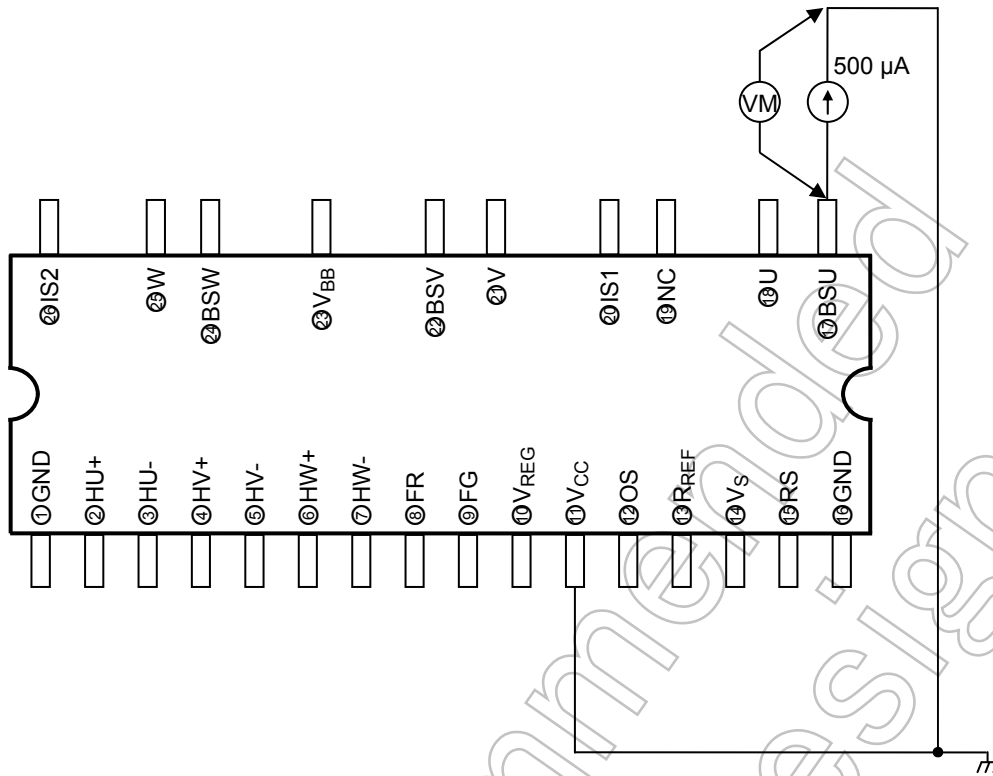


Note: Sweeps the IS/RS pin voltage and monitors the U pin voltage.  
 The IS/RS pin voltage when output is off defines the current control operating voltage.

**VS Current Dissipation (U-phase high side)**

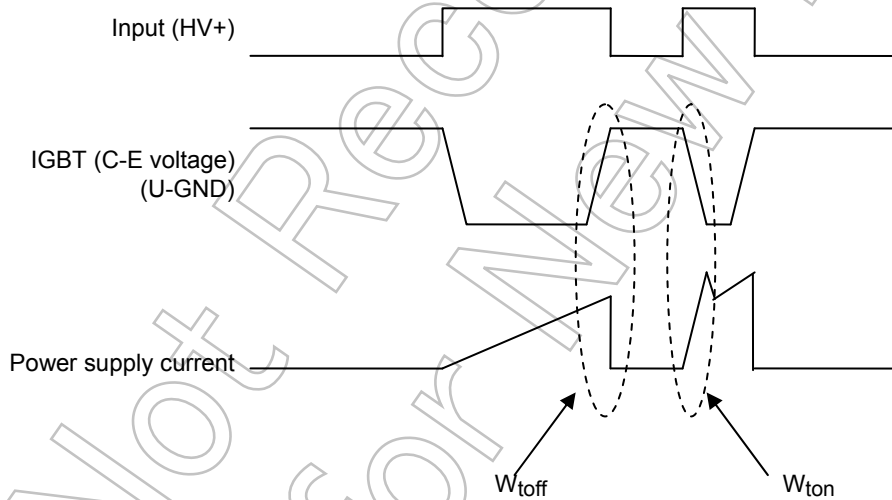
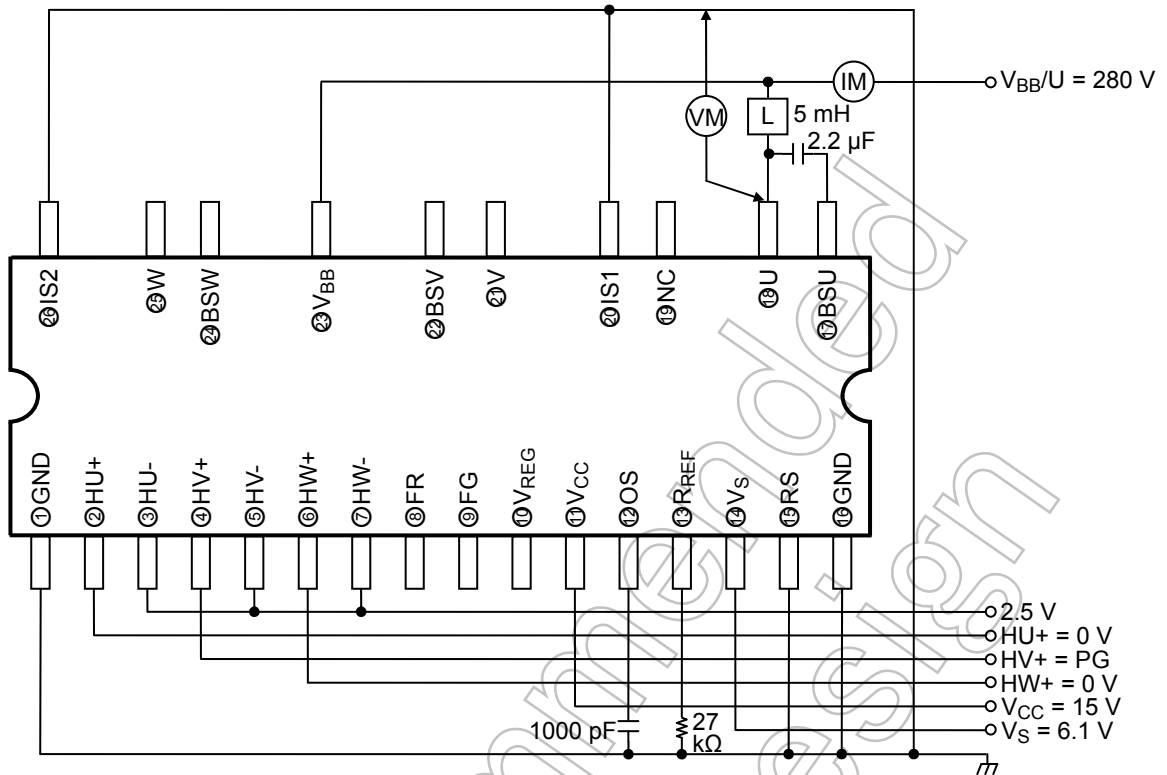


BSD Forward Voltage (U-phase)



Not Recommended for New Design

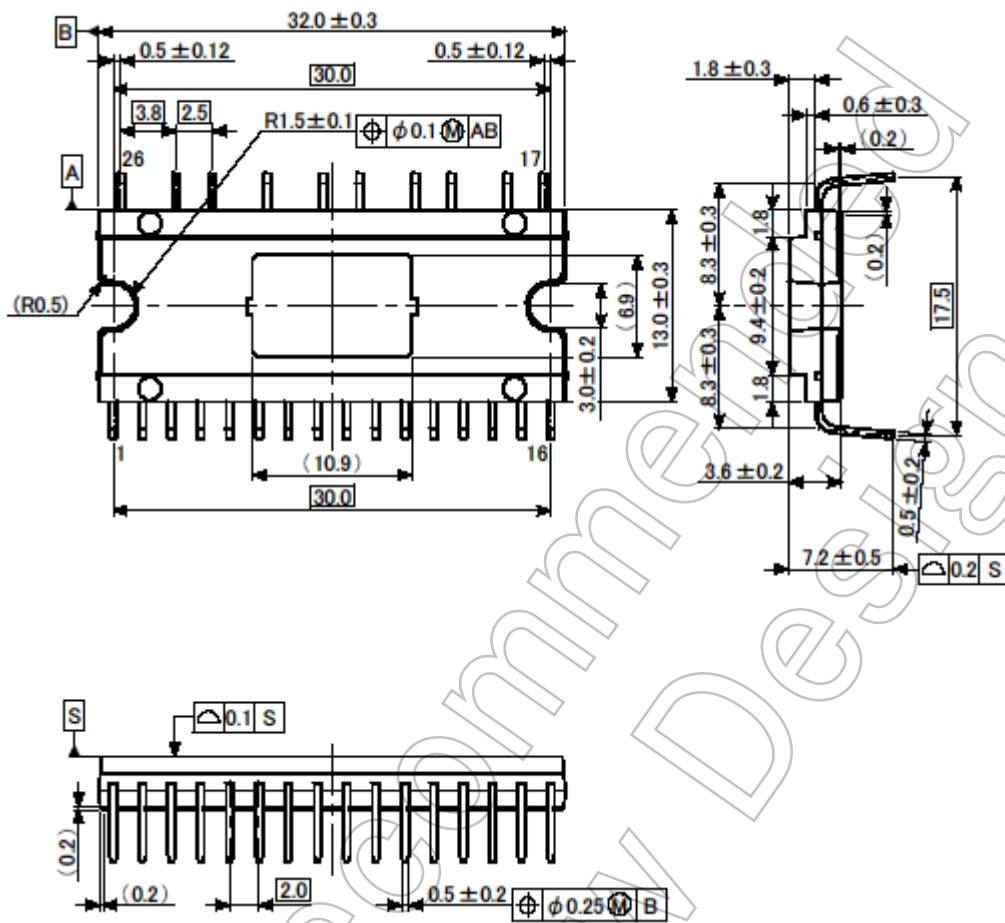
Turn-ON/OFF Loss (low side IGBT + high side FRD)



Package Dimensions

HDIP26-P-1332-2.00

Unit: mm



Weight: 3.8 g (typ.)

Not Recommended for New Design



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