

Full-Bridge DC-DC Power Supply Basic Simulation Circuit Reference Guide

RD154-RGUIDE-01

TOSHIBA ELECTRONIC DEVICES & STORAGE CORPORATION

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1. Introduction

Most electrical equipment such as including information and telecommunications equipment and home appliances operates with DC voltage.

Therefore, it is not possible to operate directly with commercial power supplied by AC voltage so it is necessary to convert from AC voltage to DC voltage.

Conversion from AC voltage to DC voltage is performed by AC-DC power supply. Depending on the power supply specifications of each load in the equipment, the DC voltage supplied by AC-DC power supply must be further converted to a DC voltage corresponding to that specification.

Fig. 1.1 shows an example of the configuration of the power supply line in the equipment. There are several power supply lines depending on the load, and the load may be connected directly to the output voltage supplied from AC-DC power supply, or the output voltage may be further converted to a different DC voltage by DC-DC power supply for connection. DC-DC power supply converts the DC voltage to a different DC voltage in this way.

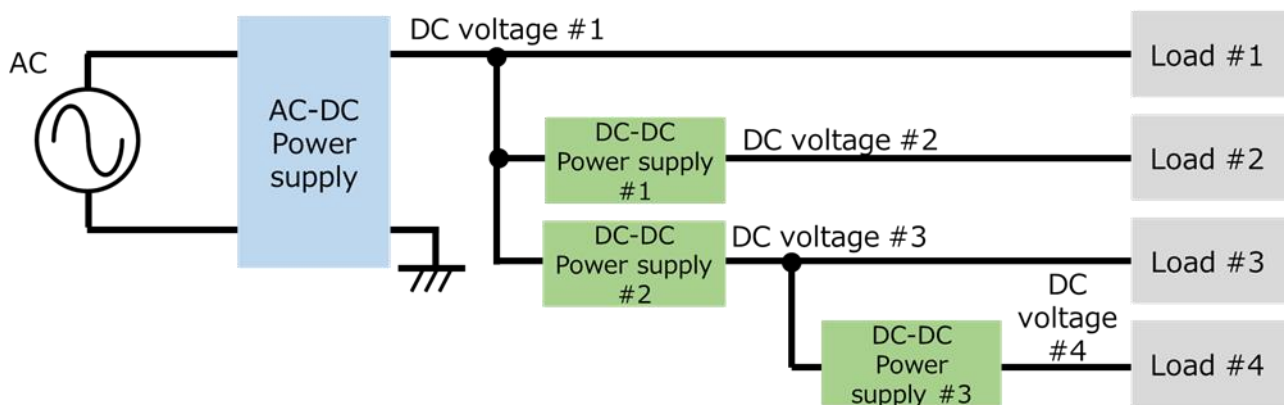


Fig. 1.1 Example of the Configuration of the power supply Line

There are two types of conversion methods from DC voltage to DC voltage: the series regulating method and the switch regulating method (hereinafter referred to as "series-base" or "switch-base").

This document deals with switch-base, which are the mainstream in DC-DC power supplies. The switch-base regulates the on/off of the switching MOSFET to generate the desired voltage. The control circuit is more complicated than the series-base, but in general, the loss can be reduced than the series-base.

There are two ways of switch-base: one is isolated DC-DC power supply, in which the input side and the output side are isolated by a transformer, and the other is non-isolated DC-DC power supply, in which the input side and the output side are not isolated. This document handles isolated DC-DC power supplies.

The isolated DC-DC power supply switches the input DC voltage at frequencies of several tens to several hundred kHz with a switching MOSFET, transmits the power to the secondary side through a transformer, rectifies, and smoothes to output the DC voltage. The final stage DC voltage is controlled by adjusting the switching MOSFET on/off period.

Fig. 1.2 shows examples of circuit blocks for isolated switch-base DC-DC power supply. It consists of two blocks: (1) DC-DC converters and (2) feedback circuits, as shown in the illustration.

The functions of each block are shown below.

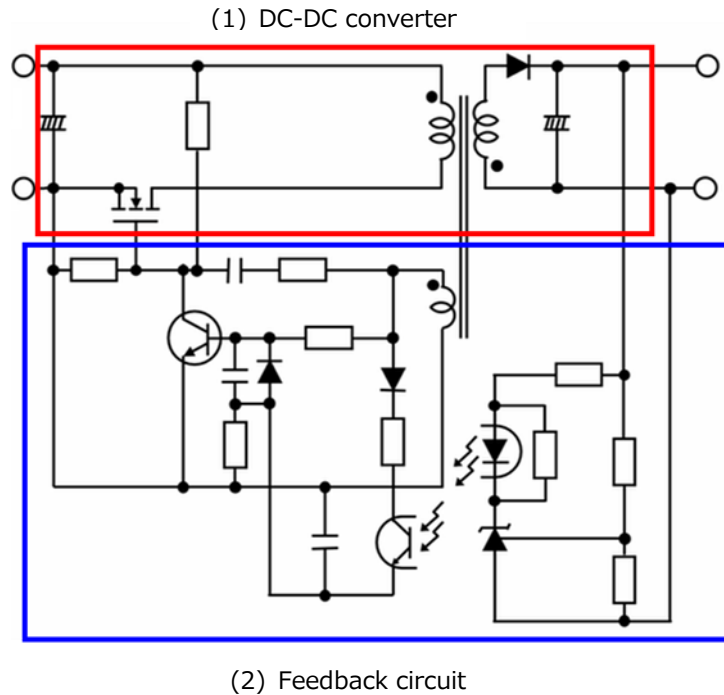


Fig. 1.2 Circuit Block for Isolated Switch-base DC-DC Power Supply

(1) DC-DC converters

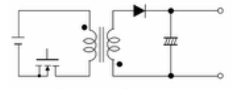
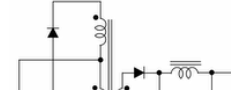
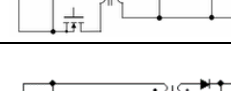
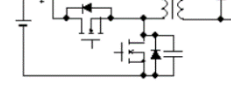
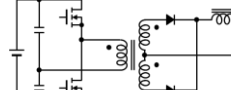

Converts the input DC voltage to any DC voltage.

(2) Feedback circuit

The switching MOSFET is controlled so that the output voltage becomes a desired value.

There are a variety of topologies for DC-DC converters. Table 1.1 shows typical topologies and characteristics of DC-DC converters.

Table 1.1 Typical Topologies and Characteristics of DC-DC Converters

Circuitry of DC-DC converter section	Power level	Advantages	Disadvantages
Flyback 	< 200 W	<ul style="list-style-type: none"> • Small part count 	<ul style="list-style-type: none"> • Reduction in efficiency at high power • Large transformer
Forward 	50 W~500 W	<ul style="list-style-type: none"> • Higher efficiency than a flyback circuit 	<ul style="list-style-type: none"> • Transformer reset circuit required
Active clamp forward 	50 W~500 W	<ul style="list-style-type: none"> • Higher Efficiency than a forward 	<ul style="list-style-type: none"> • There are many parts • Be difficult to control
Half-bridge 	100 W~1 kW	<ul style="list-style-type: none"> • High efficiency • Low noise 	<ul style="list-style-type: none"> • Specially designed transformer is required. • Be difficult to control
Resonant half bridge (LLC resonance) 	100 W~1 kW	<ul style="list-style-type: none"> • High efficiency than a half bridge • Low noise 	<ul style="list-style-type: none"> • Specially designed transformer is required. • Be difficult to control
Full-bridge 	> 200 W	<ul style="list-style-type: none"> • High efficiency • Capable of increasing the power capacity 	<ul style="list-style-type: none"> • There are many parts • Be difficult to control

Regarding the basic operation of the full-bridge method, we are distributing it on our web. Please also refer to the video below.

The Video of the full-bridge DC-DC converter are shown here →

[Click Here](#)

The full-bridge method described in this document is widely used in power supplies requiring high efficiency and high power density, because the power supply input voltage applies the primary side of the transformer directly due to cross coupled two switching elements of four switching elements located on the primary side of the transformer turn on/off at the same timing.

Toshiba provide basic simulation circuits (RD154-SPICE-01) on our web to understand full-bridge DC-DC converter circuit operation in switch-base DC-DC power supplies.

This document provides an overview of this basic simulation circuit and explains how to use it. The Cadence's Capture and PSpice[®] A/D tools are required to operate the simulator circuits from OrCAD. Simulation circuits and documentation have been prepared in accordance with OrCAD 17.2.

2. Outline of Full-Bridge DC-DC Power Supply

The basic simulation circuit (RD154-SPICE-01) is a 200 W full-bridge DC-DC power supply.

2.1 Power Supply Specifications

The full-bridge DC-DC power supply specifications described in this document are as follows:

- Input voltage (V_{in}) : 24 V
- Output voltage (V_{out}) : 5 V
- Output current (I_{out}) : 0~40 A
- Secondary MOSFET operating frequency: 65 kHz (twice the primary operating frequency)
- Winding ratio: $n1:n2:n3= 5:2:2$
- Allowable ripple current width on the secondary side (ΔI_{ripple}) : 20 %

2.2 Circuit Configuration

Fig. 2.1 shows the simulation circuit for OrCAD®. This is a full-bridge type DC-DC converter power supply, which mainly consists of a power section (full-bridge) and a PWM controller section. The secondary side of the power section is a synchronous rectification circuit using MOSFETs. The PWM controller section is a general-purpose controller with a built-in MOSFET gate driver, which is provided to realize PWM circuit. The switching MOSFETs are "TPN11006PL" and "TPH1R204PL" as examples.

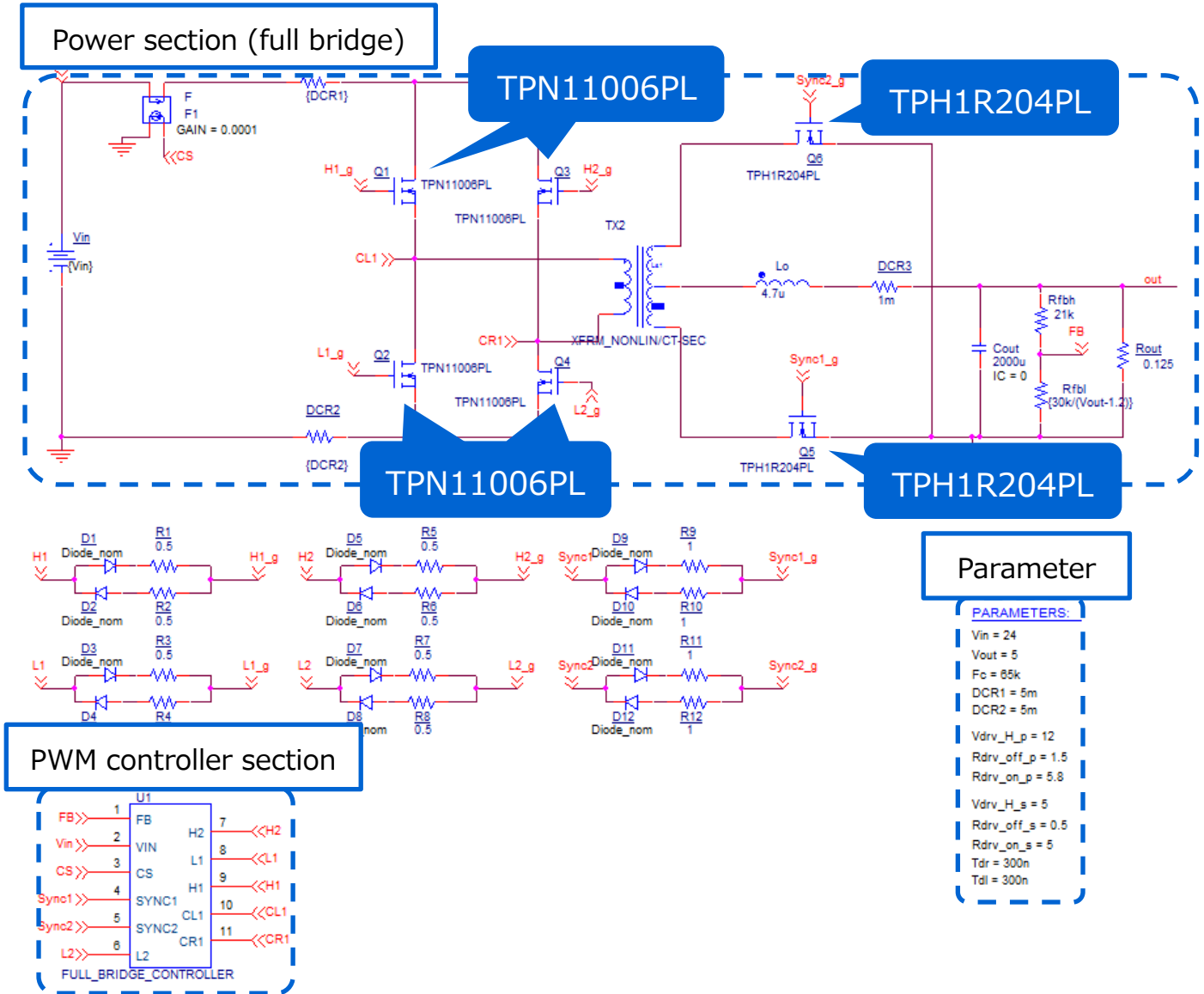


Fig. 2.1 Simulation circuit of 200 W Full-Bridge (DC-DC Converter) Power Supply

Selection of primary side MOSFET

Primary side MOSFET(TPN11006PL: $V_{DSS}=60$ V, $I_D=26$ A) is selected from the following viewpoints.

(1) Breakdown-voltage

The voltage applied to the MOSFET at static state is the input voltage (=24 V). Select a MOSFET with a breakdown-voltage of 60 V or higher, considering the surge voltage at the time of switching and other factors.

(2) Current rating

When the input current is maximum, it is at the maximum output power. If the conversion efficiency at the maximum output power (=200W) is 90%, the maximum average input current is 9.3 A. Select a MOSFET with a current rating of 19 A or more.

Here, we selected a 26 A current MOSFET from our product lineup.

Selection of secondary side MOSFET

Secondary side MOSFET(TPH1R204PL: $V_{DSS}=40$ V, $I_D=150$ A) is selected from the following viewpoints.

(1) Breakdown-voltage

Since the winding ratio is 5:2, the voltage between the middle point and both ends of the secondary winding at static state is 9.6 V, which is 2/5 of the input voltage, and 19.2 V, which is twice the voltage, is applied to each MOSFET on the secondary side.

A surge voltage is generated when the transformer current is switched. Select a MOSFET with a breakdown-voltage of 40 V or more.

(2) Current rating

When the output current is maximum, it is at the maximum output power. The maximum output current of 40 A at maximum output power (=200 W) is shared by MOSFET of the two current paths on the secondary side, a current of 20 A flows per path. Therefore, a MOSFET with a current rating of 40 A or more is required. In addition, select a MOSFET with as low an on-resistance as possible with emphasis on suppressing conduction loss.

Selection of output inductor

This section explains how to select the output inductor on the secondary side. The inductance value of the output inductor in this simulation circuit can be calculated using the following items, which are power supply specifications.

- Input voltage: V_{in} (V) = 24
- Transformer winding ratio: $n_2/n_1=n_3/n_1 = 2/5$
- Output Voltage: V_{out} (V) = 5
- Switching frequency: F_c (Hz) = 65k
- Max. output current: I_{out_max} (A) = 40
- Allowable ripple current range: ΔI_{ripple} (%) = 20

The inductance value (L_o) of the output inductor is calculated by the following formula.

$$L_o = \frac{\left(\frac{n_2}{n_1} \times V_{in} - V_{out}\right) \times V_{out}}{\frac{n_2}{n_1} \times V_{in} \times F_c \times I_{out_max} \times \Delta I_{ripple} \times 0.01}$$

The inductance value (L_o) of the output inductor is calculated as 4.61 μH from the above equation, and 4.7 μH is selected as the setting value from the power supply specifications of this model. In the actual design, the inductance value of the inductor changes due to the DC superposition characteristic. Select a component that can secure the calculated value in a state where the inductance value is lowered due to the DC superposition characteristic.

3. Simulation Result

The operation simulation waveforms of each part in the simulation circuit are shown by the points in Fig. 3.1 ((1) to (4)).

- (1) Full-bridge basic operation ("Primary MOSFET Drain-Source Voltage")
- (2) Secondary-side synchronous rectification operation ("Secondary-side MOSFET drain/source voltage/current")
- (3) Output inductor voltage and current at both ends
- (4) "Output voltage and current" as a power supply

When actually using the circuit model, it is possible to display the waveform at any point other than those shown in Fig. 3.1. The waveform display method is described in Chapter 5.

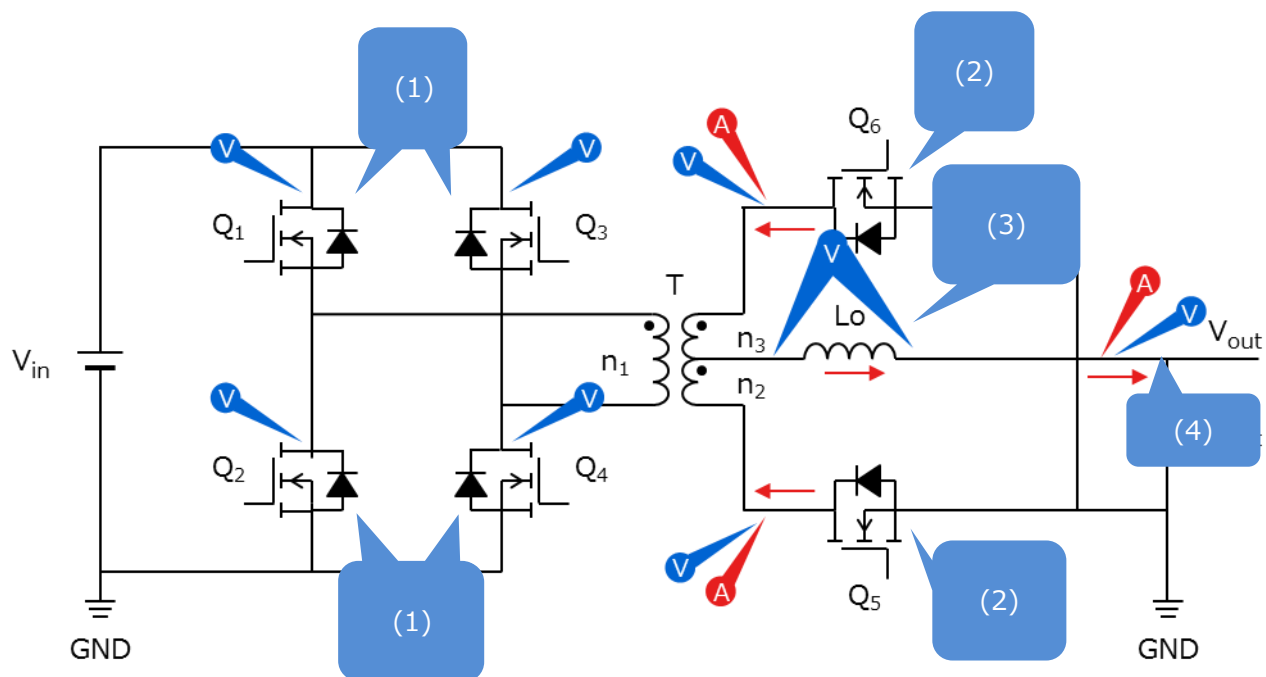
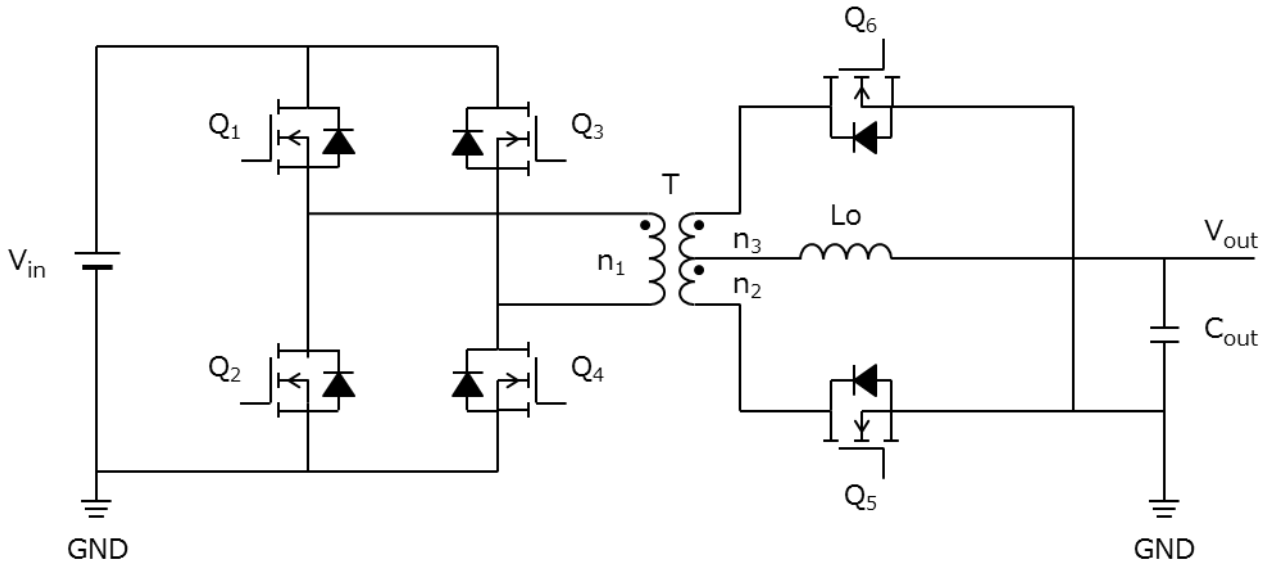


Fig. 3.1 Simulation Waveform Measurement Point List

(1) Full-bridge basic operation

The basic operation of the full-bridge method is described in Fig. 3.2, which shows the full-bridge circuit.



Q₁~Q₄: Primary MOSFET
 Q₅, Q₆: Secondary MOSFET
 L_o: Output inductor

Fig. 3.2 Full-Bridge Circuit

In the full-bridge method, Q₁ and Q₄, Q₃ and Q₂ are alternately turned on and off in pairs, respectively, and the output voltage is controlled using PWM (pulse-width modulation) control.

For the output-voltage V_{out}, it can be calculated by:

$$V_{out} = 2 \times \frac{n_2}{n_1} \times V_{in} \times \frac{T_{on}}{T}$$

T: Period of the primary side

T_{on}: On-time

A. Q₁ and Q₄ are on, Q₃ and Q₂ are off

This is the period during power is transferred from the primary side to the secondary side. The primary winding voltage at this time is the input voltage (V_{in}). For the secondary winding, the voltages corresponding to the winding ratios are given with the polarity symbol of the n₂ as positive.

$$\frac{n_2}{n_1} \times V_{in}$$

The voltage is applied to the L_o via the Q_5 ,

$$\Delta i_{L_o(Q1,Q4_on)} = \frac{1}{L_o} \left(\frac{n_2}{n_1} \times V_{in} - V_{out} \right) \times T_{on}$$

The current determined by the equation increases linearly to charge the C_{out} and provide the output current I_{out} . At this time, magnetic energy is stored in the L_o .

B. Q_1 , Q_2 , Q_3 and Q_4 are off

The energy stored in the L_o flows into the Q_5 and Q_6 . To the L_o at this time, the current decrease lineally as follows.

$$\Delta i_{L_o(all_off)} = \frac{-V_{out}}{L_o} \times \left(\frac{T}{2} - T_{on} \right)$$

C. Q_1 and Q_4 are off, Q_2 and Q_3 are on

This is the period during power is transferred from the primary side to the secondary side. During this period, the primary winding voltage becomes $-V_{in}$. For the secondary winding, the voltage corresponding to the winding ratio is applied with the polarity symbol side of the n_3 taken as a minus.

$$\frac{n_3}{n_1} \times V_{in}$$

This voltage is applied to the L_o via the Q_B , the current flows as follow:

$$\Delta i_{L_o(Q3,Q2_on)} = \frac{1}{L_o} \times \left(\frac{n_3}{n_1} \times V_{in} - V_{out} \right) \times T_{on}$$

D. Q_1 , Q_2 , Q_3 and Q_4 are off

The energy stored in the L_o flows into Q_5 and Q_6 , the current flows as follow:

$$\Delta i_{L_o(all_off)} = \frac{-V_{out}}{L_o} \times \left(\frac{T}{2} - T_{on} \right)$$

Fig. 3.3 shows the primary-side MOSFET drain-source voltage and output inductor voltage/current waveforms.

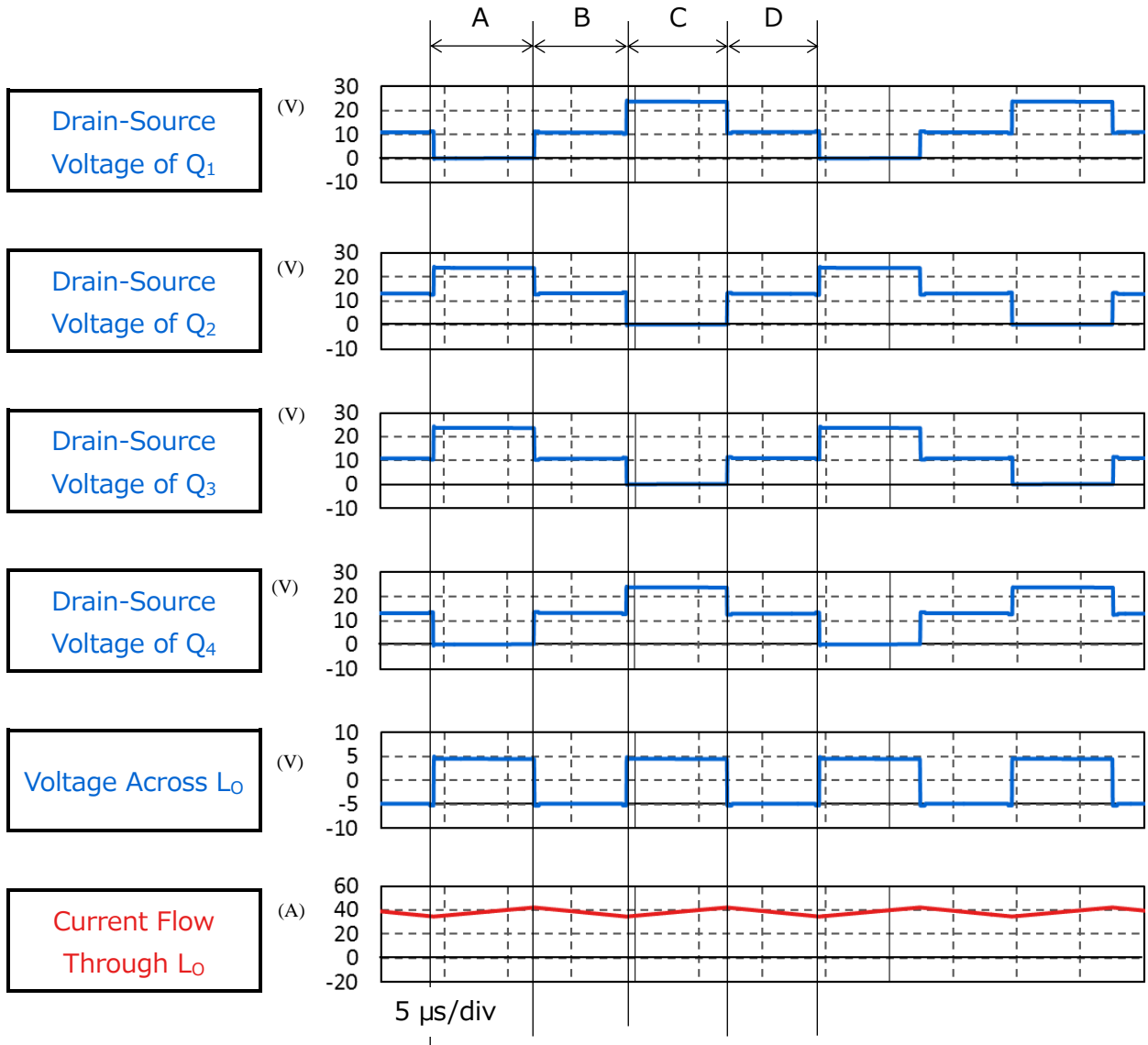


Fig. 3.3 Primary MOSFET Drain-Source Voltage/Current, Output Inductor Voltage/Current

(2) Secondary side synchronous rectification operation

This simulation model uses a synchronous rectifier circuit that uses MOSFET instead of diodes for the secondary rectifier. Generally, the conduction loss due to the on-resistance of the MOSFET is smaller than that of the diode so the synchronous rectifier circuit can reduce the conduction loss. The larger output current, the greater loss reduction effect of the synchronous rectifier circuit, and is often used in applications where high efficiency and large capacity are required.

The operation of the secondary MOSFET in the respective periods are as follows.

a. Q₅ is off, Q₆ is on

Voltage corresponding to the winding ratio with the polarity symbol side of the secondary side winding n₂ as plus voltage,

$$\frac{n_2}{n_1} \times V_{in}$$

is applied and current flows through Q₅ to L_o.

b. Q_A is on, Q_B is on

Electric power stored in the L_o recirculates through the Q₅ and Q₆.

c. Q₅ is on, Q₆ is off

Voltage corresponding to the winding ratio with the polarity symbol side of the secondary side winding n₃ as a minus voltage

$$\frac{n_3}{n_1} \times V_{in}$$

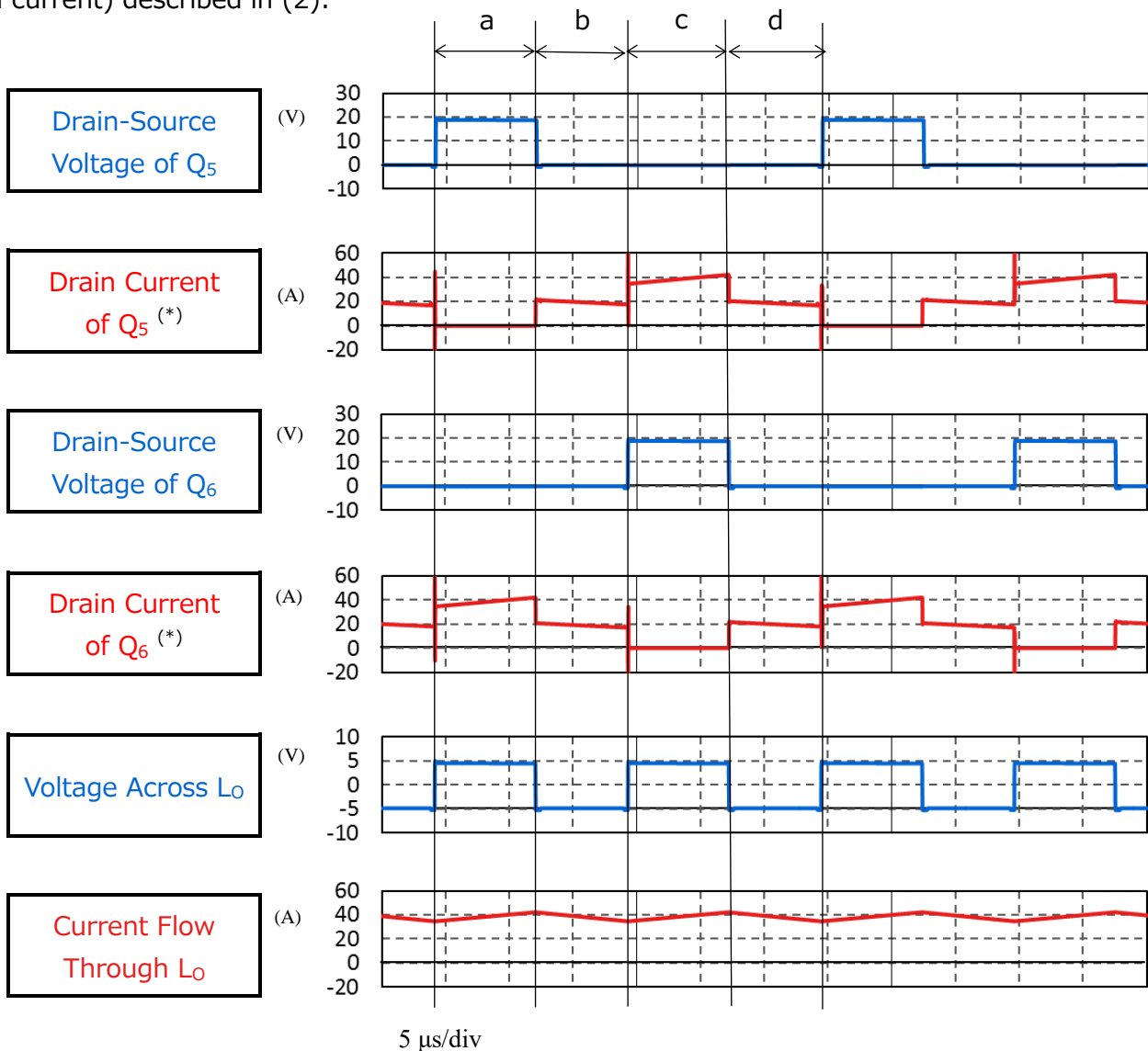
is applied and current flows through Q₆ to L_o.

d. Q₅ is on, Q₆ is on

Electric power stored in the L_o recirculates through the Q₅ and Q₆.

(3) Output inductor voltage and current at both ends

Fig. 3.4 shows the output inductor voltage and current waveforms in conjunction with the secondary-side synchronous rectification operation (secondary-side MOSFET drain-source voltage and current) described in (2).



* : Drain current is positively directed from MOSFET to the transformer secondary winding.

Fig. 3.4 Secondary-Side MOSFET Drains/Source Voltage/Current Output Inductor Voltage/Current Waveforms

(4) "output voltage and current" as a power supply

Fig. 3.5 shows the output voltage and current waveforms of this power supply circuit. It can be seen that it is stable at the set voltage and current.

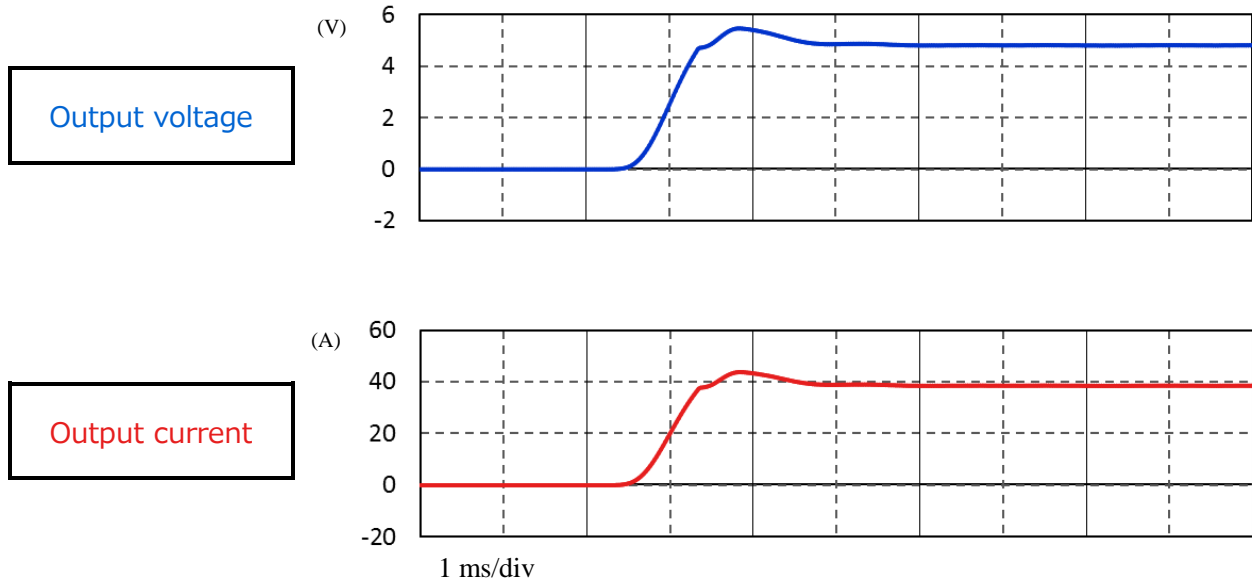


Fig. 3.5 Output Voltage and Current Waveforms

4. Product Overview

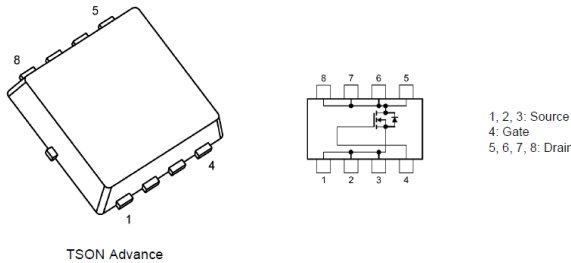
This section provides an overview of our products that have been tested by incorporating PSpice® models into the circuits.

4.1 TPN11006PL

Features

- $V_{DSS}=60\text{ V}$, $I_D=26\text{ A}$
- High speed switching
- Small gate-input charge: $Q_{SW} = 5.8\text{ nC}$ (Typ.)
- Small power charge: $Q_{OSS} = 14.4\text{ nC}$ (Typ.)
- Low on-resistance: $R_{DS(ON)}=8.8\text{ m}\Omega$ (Typ.) ($V_{GS}=10\text{ V}$)
- Lower leakage current: $I_{DSS} = 10\text{ }\mu\text{A}$ (Max.) ($V_{DS}=60\text{ V}$)
- Easy-to-handle enhancement type: $V_{th} = 1.5\text{ to }2.5\text{ V}$ ($V_{DS}=10\text{ V}$, $I_D=0.2\text{ mA}$)

Appearance and terminal arrangement



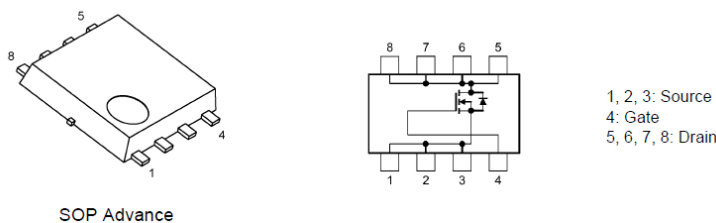
Width 3.3 × Length 3.3 × Height 0.85 (mm)

4.2 TPH1R204PL

Features

- $V_{DSS}=40\text{ V}$, $I_D=150\text{ A}$
- High speed switching
- Small gate-input charge: $Q_{SW} = 17\text{ nC}$ (Typ.)
- Small power charge: $Q_{OSS} = 56\text{ nC}$ (Typ.)
- Low on-resistance: $R_{DS(ON)}=1.0\text{ m}\Omega$ (Typ.) ($V_{GS}=10\text{ V}$)
- Lower leakage current: $I_{DSS} = 10\text{ }\mu\text{A}$ (Max.) ($V_{DS}=40\text{ V}$)
- Easy-to-handle enhancement type: $V_{th} = 1.4\text{ to }2.4\text{ V}$ ($V_{DS}=10\text{ V}$, $I_D=0.5\text{ mA}$)

Appearance and terminal arrangement



Width 5.0 × Length 6.0 × Height 0.95 (mm)

5. Using the Simulation Circuit

In order to verify the operation according to actual specifications and the changes according to circuit constants, the simulator can freely change various parameters and analyze the operation of the simulator on OrCAD's Capture. This section describes how to set parameters and how to analyze the operation when actually performing a simulation.

How to set parameters

Table 5.1 lists the parameters that can be set by the simulation circuit. Double-clicking a variable in the parameter setting section displays the "Display Properties" window shown in Fig. 5.1. Change the "Value" value in that window.

Table 5.1 List of Variables Settable in Parameter Setting Section

Variable name	Unit	Description
Vin	V	Input voltage
Vout	V	Output voltage
Fc	Hz	Switching frequencies of the secondary MOSFET
DCR1	Ω	Primary power plane parasitic resistance
DCR2	Ω	GND plane parasitic resistance value on the primary side
Vdrv_H_p	V	Power supply voltage of the primary gate driver
Rdrv_off_p	Ω	Primary MOSFET Internal resistance of gate driver (off side)
Rdrv_on_p	Ω	Primary MOSFET Internal resistance of gate driver (on side)
Vdrv_H_s	V	Power supply voltage of the secondary gate driver
Rdrv_off_s	Ω	Secondary MOSFET Internal resistance of gate driver (off side)
Rdrv_on_s	Ω	Secondary MOSFET Internal resistance of gate driver (on side)
Tdr	Sec	Dead time in Q3 and Q4
Tdl	Sec	Dead time of the legs of Q1 and Q2

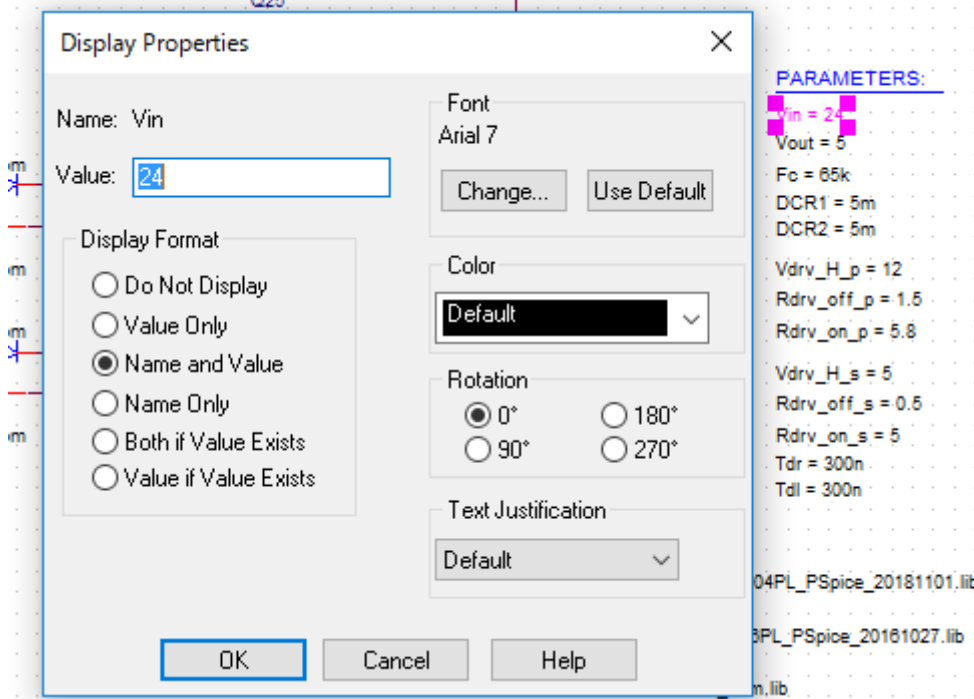


Fig. 5.1 Parameter setting screen

How to set analysis

The procedure for executing the simulation of this simulation circuit is described below.

- (1) The "New Simulation" window shown in Fig. 5.2 is displayed by clicking "PSpice"- "New Simulation Profile" on OrCAD's Capture menu bar. Specify any profile names and click "Create".

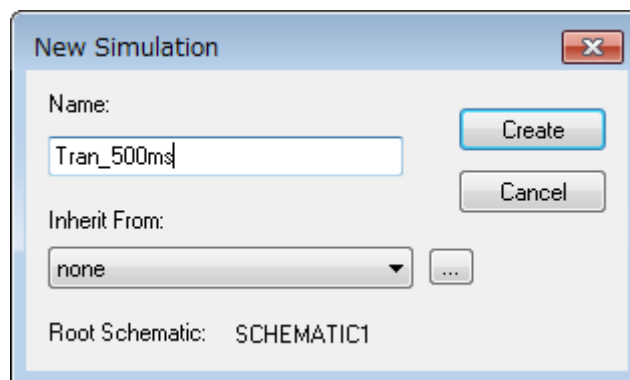


Fig. 5.2 New Simulation window

- (2) After the steps in 1., the "Simulation Settings" window shown in Fig. 5.3 is displayed, allowing various analysis settings to be made. First, set the analysis method in Analysis tab. Specify "Time Domain(Transient" for "Analysis Type". Specify the duration of the analysis in "Run To Time" and the largest step length in the analysis in "Maximum Step Size".

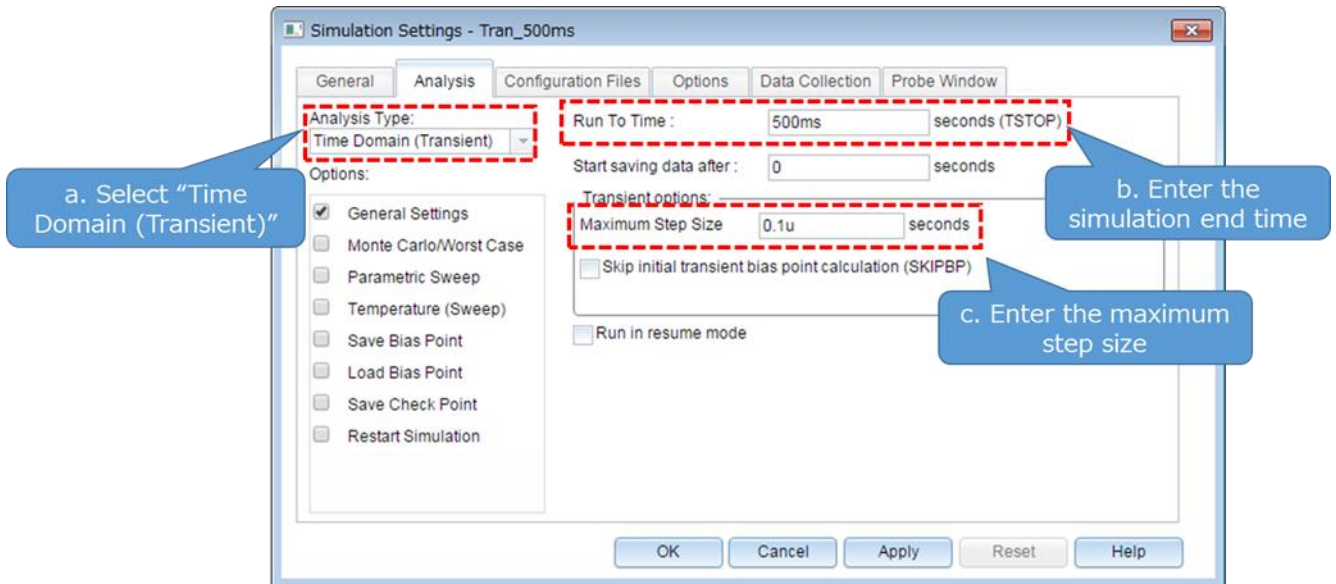


Fig. 5.3 Simulation Settings"- "Analysis window

- (3) Set analysis options in Options tabs It is recommended to activate the auto-convergence function by checking the "Analog Simulation"- "Auto Converge"- "AutoConverge" checkbox as shown in Fig. 5.4.

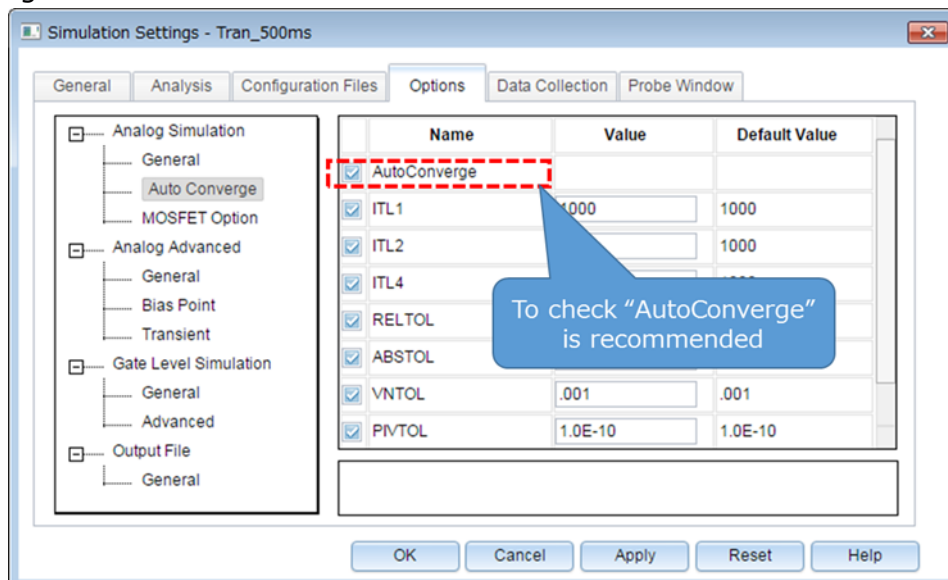


Fig. 5.4 Simulation Settings"- "Options window

- (4) When the above settings are completed, click "OK" and close the "Simulation Settings" window.
 (5) Execute simulations at "PSpice"- "Run" on OrCAD "Capture" menu bar. PSpice A/D starts automatically and the simulations are executed.

How to check the results

This section describes how to check the results after completion of simulation. There are two methods for displaying the result waveforms on PSpice A/D window. The procedures for each method are described below.

Method 1. Result display with net name specified

- (1) Right-click outside the graph frame in the graph window, and then select "Add Trace". (Fig. 5.5)
- (2) Select the waveforms to be displayed from the "Add Traces" window. Select V (net name) for the voltage waveform and I (element name) for the current waveform. (Fig. 5.6)
- (3) After selecting, click "OK" to display the result waveform. (Fig. 5.7)

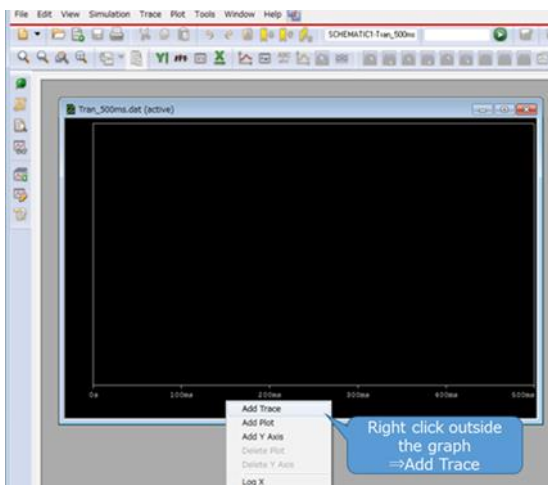


Fig. 5.5 Graph Window

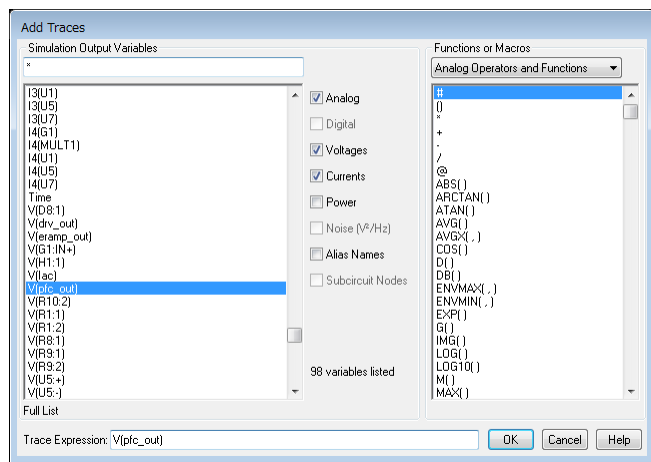


Fig. 5.6 "Add Traces" Window

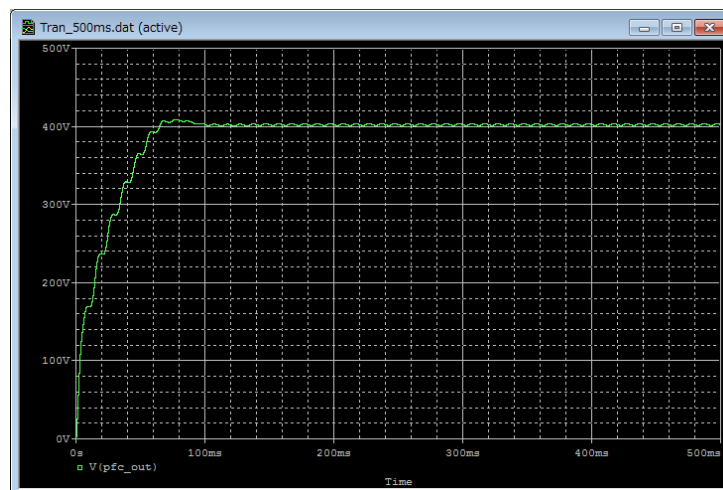


Fig. 5.7 Result Waveform Display (Example: Output Voltage Waveform)

Method 2. Displaying the result using Marker function

- (1) Select Marker type according to the waveform to be displayed from "PSpice"->"Markers" on OrCAD's Capture menu bar. (Fig. 5.8)
- (2) Place Marker at the waveform measuring points on the simulator. (Fig. 5.9)
- (3) The result waveforms are displayed in the graph window of PSpice A/D. (Fig. 5.10)

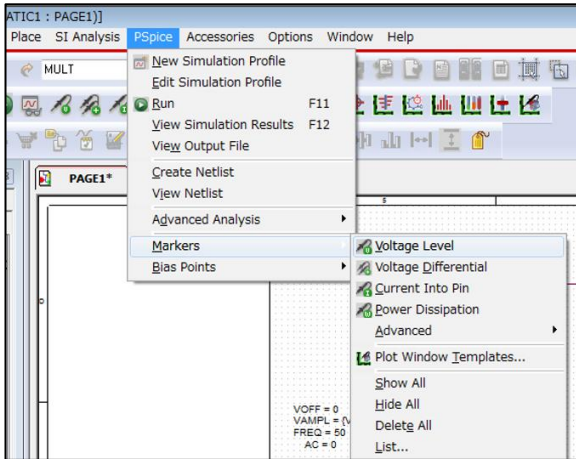


Fig. 5.8 Selecting a Marker type

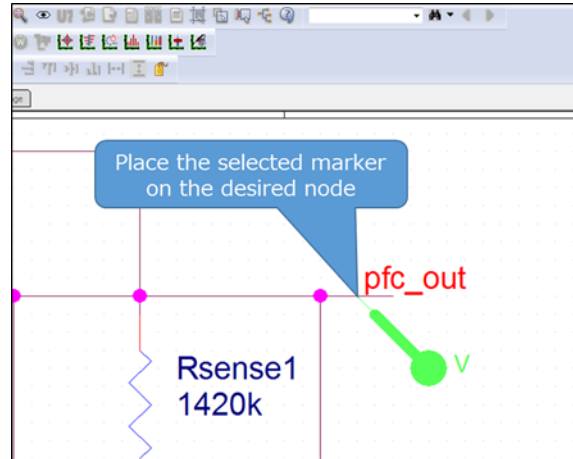


Fig. 5.9 Placing a Marker in the circuits

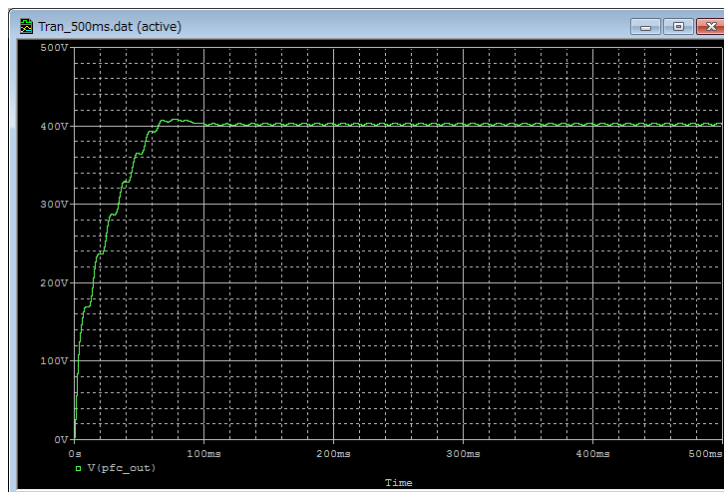


Fig. 5.10 Simulation Waveform View (Example: Output Voltage Waveform)

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