

Application Note

CG_RTC

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1. Preface

This application note describes sample software for the switches between NORMAL mode and low power consumption mode using clock control and operation mode functions. This document helps the user check operation of a product under development and develop its program.

2. Technical Term

Term/Abbreviation	Definition
CG	Clock control and Operation Mode
BSP	Board Support Package
RTC	Real Time Clock
Timer	T32A : 32-bit Timer Event Counter

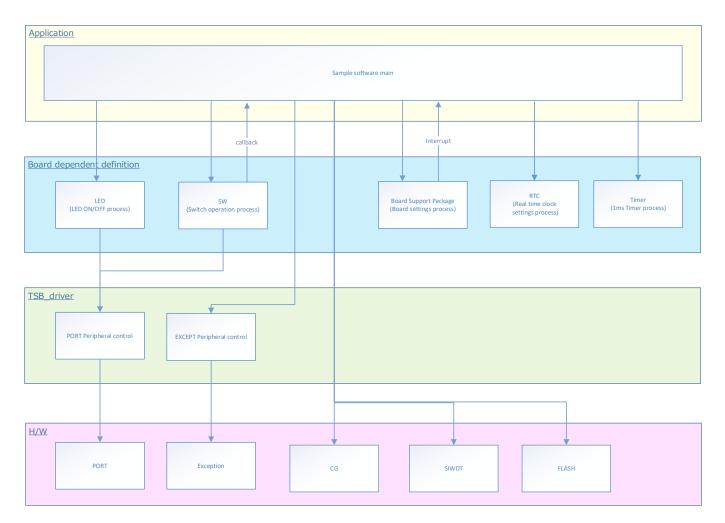
3. Reference Document

Document	Notes
Data sheet	Refer to the data sheet of MCU to be used.
Reference manual	Refer to the reference manual of each IP to be used.
Application note MCU User Guide	Refer to the MCU user guide to be used.

4. Target Sample Program

Sample Program	Outline
CG_RTC	Sample program of clock control and operation mode switching

5. Configuration Diagram



6. Sample Program : CG_RTC

This is sample software that uses Push-Switch input and RTC as a trigger to switch the mode of the microcomputer.

6.1. Outlines of Operation

Switch to low power consumption mode (IDLE / STOP1 / STOP2) triggered by port input by Push-Switch. When shifting to the low power consumption mode, the LED lights up and you can check the operation switching.

After switching to the low power consumption mode, it will return to NORMAL mode after 1 minute by RTC.

6.1.1. NORMAL Mode

In NORMAL mode, the following operations are performed.

- BSP_LED_1 blinks in Cycle_A and Duty_A (other LEDs are off).
- Port input monitoring (monitoring at intervals).
- Press BSP_PSW_1 to switch to IDLE mode.
- Press BSP_PSW_2 to switch to STOP1 mode.
- Press BSP_PSW_3 to switch to STOP2 mode.

6.1.2. Low power consumption Mode

In the low power consumption mode, the following operations are performed.

IDLE

- BSP LED 2 is on (other LEDs are off).
- After 1 minute by RTC, it shifts to NORMAL mode.

STOP1

• BSP_LED_3 is on (other LEDs are off).

• After 1 minute by RTC, it shifts to NORMAL mode.

STOP2

• BSP_LED_4 is on (other LEDs are off).

• After 1 minute by RTC, it shifts to NORMAL mode.

6.2. Function to Use

The functions to use are as follows.

For the Port assignment of each channel, refer to the MCU user guide.

IP	Channel	Objective	
PORT	BSP_PSW_1	For event triggers	
	BSP_PSW_2	For event triggers	
	BSP_PSW_3	For event triggers	
	BSP_LED_1	For operation check	
	BSP_LED_2	For operation check	
	BSP_LED_3	For operation check	
	BSP_LED_4	For operation check	
RTC	-	RTC for event triggers	
T32A	BSP_T32A_TIMER_1	Used as a 1ms interval timer	

6.3. Interrupt to Use

Interrupt	Outlines
INTRTC	RTC interrupt. For returning from IDLE / STOP1 / STOP2
INTT32A00A	T32A Timer A
	Timer counter increments every 1ms for Switch / LED processing

6.4. Configuration

"main.c" configuration setting.

Configuration	Current Value	Description
Cycle_A	2Hz	-
Duty_A	50%	-
Timer_A	1m	-

6.5. Example of Terminal Emulator Output

Nothing.

7. CG Driver

The CG is controlled by using the following driver. For an example of use, refer to the source code.

Driver	Control Outlines		
cg_set_gear	Set the gear according to the register value		
cg_set_phyt0	Set the pre-scaler clock according to the register value		
cg_set_warm_up_time	Set warm-up time		
cg_start_warmup	Start operation of warm-up timer for oscillator		
cg_get_warm_up_state	Check if the warm-up is complete		
cg_wait_warmup	Wait for the warm-up end of high-speed oscillation		
cg_set_ehoscen	Select an external high speed oscillator		
cg_set_oscsel	Set FOSC base clock		
cg_get_oscsel	Check if it is in oscsel state		
cg_get_gear	Update gear according to register value		
cg_get_phyt0	Update prescaler clock according to register value		
cg_ihosc1_enable	Enable internal high speed oscillator 1		
cg_ihosc1_disable	Disable internal high speed oscillator 1		
cg_set_PLL	Set the PLL according to the register value		
cg_PLL_enable	Enable PLL		
cg_PLL_disable	Disable PLL		
cg_set_stby_mode	Set STBYmode according to register value		
cg_set_PLL_clock	Set PLL base clock		
cg_get_PLL_status	Check if it is in PLL0SEL state		
cg_protect_enable	Enable CG protection		
cg_protect_disable	Disable CG protection		
cg_get_ihosc1_state	Check if it is in ihosc1 state		
cg_get_ihosc2_state	Check if it is in ihosc2 state		
cg_ihosc2_enable	Enable internal high speed oscillator 2		
cg_ihosc2_disable	Disable internal high speed oscillator 2		
cg_scout_enable	Enable SCOUT		
cg_scout_disable	Disable SCOUT		
cg_set_scout_clock	Set SCOUT base clock		
cg_set_scout_time	Set SCOUT time		
cg_get_stby_mode	Get TRBY mode register value		
cg_set_low_warm_up_time	Set low oscillator warm-up time		
cg_start_low_warmup	Start operation of warm-up timer for low oscillator		
cg_get_low_warm_up_state	Check if low oscillator warm-up is complete		
cg_get_system_core_clock	Get CG system core clock		
rlm_port_keep_enable	Enable RLM port		
rlm_port_keep_disable	Disable RLM port		
rlm_protect_enable	Enable RLM protection		
rlm_protect_disable	Disable RLM protection		
 rlm_fs_enable	Enable fs		
 rlm_fs_disable	Disable fs		

8. Revision History

Revision	Date	Description
1.0	2023-06-28	First release

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