

Application Note

UART_HalfClockReceive

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1. Preface

This application note describes sample software for the UART half clock mode reception control function. This document helps the user check operation of a product under development and develop its program.

2. Technical Term

| Term/Abbreviation | Definition |
|-------------------|---|
| UART | Universal Asynchronous Receiver Transmitter |
| BSP | Board Support Package |
| Timer | T32A : 32-bit Timer Event Counter |
| CG | Clock control and Operation Mode |

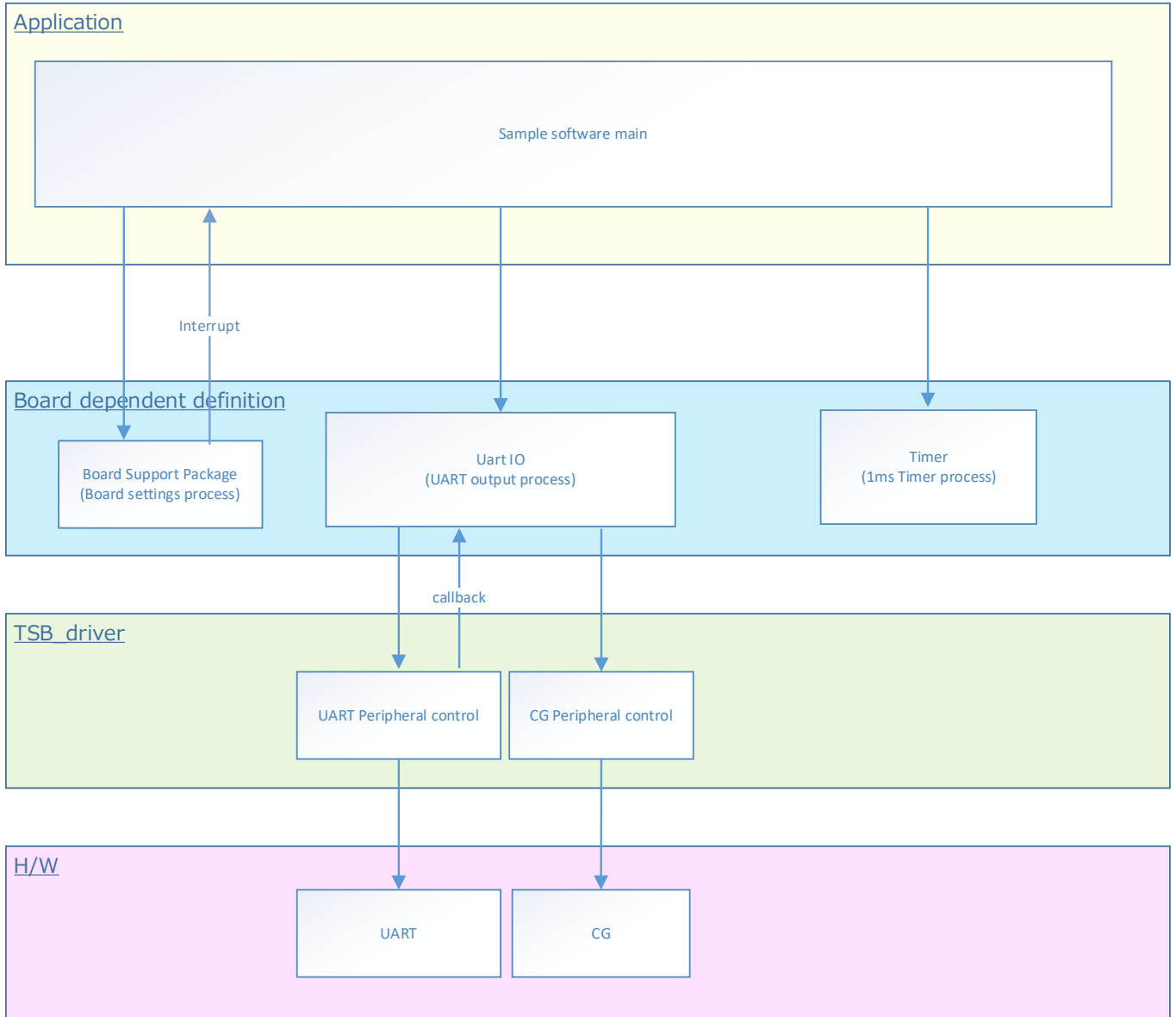
3. Reference Document

| Document | Notes |
|------------------------------------|--|
| Data sheet | Refer to the data sheet of MCU to be used. |
| Reference manual | Refer to the reference manual of each IP to be used. |
| Application note MCU User Guide | Refer to the MCU user guide to be used. |

4. Target Sample Program

| Sample Program | Outline |
|-----------------------|--|
| UART_HalfClockReceive | Sample program of UART_HalfClockReceive function |

5. Configuration Diagram



6. Sample Program : UART_HalfClockReceive

This is sample software that sends the data received in half clock mode to the terminal emulator.

6.1. Outlines of Operation

Receives the data input to the terminal emulator in UART half clock mode.

6.2. Function to Use

The functions to use are as follows.

For the Port assignment of each channel, refer to the MCU user guide.

| IP | Channel | Objective |
|------|------------|---|
| UART | BSP_UART_1 | For terminal emulator communication. Used for operation log output and command input |
| | BSP_UART_2 | For applications. Half Clock control |

6.3. Interrupt to Use

| Interrupt | Outlines |
|-------------|--|
| INTT32A00A | T32A ch0 Timer_A Timer counter increment every 1ms |
| INTUART0TX | UART ch0 Receive interrupt for terminal emulator |
| INTUART0RX | UART ch0 Transmission interrupt for terminal emulator |
| INTUART0ERR | UART ch0 Error interrupt for terminal emulator |
| INTUART3RX | UART ch3 Receive interrupt. For board A / B communication |
| INTUART3TX | UART ch3 Transmission interrupt. For board A / B communication |
| INTUART3ERR | UART ch3 Error interrupt. For board A / B communication |

6.4. Configuration

“main.c” configuration setting.

| Configuration | Current Value | Description |
|---------------|---------------|---------------|
| MAX_DATA | 32 | 32 characters |

6.5. Example of Terminal Emulator Output

6.5.1. Normal Operation

```
Input = 12345  
Echo = 12345
```

6.5.2. Case of Error Occurrence

```
Input = 123456789012345678901234567890123  
Input Error !!
```

7. UART Driver

The UART is controlled by using the following interface.
For an example of use, refer to the source code.

| Driver | Control Outlines |
|---------------------------|--|
| uart_init | UART Object initialization |
| uart_deinit | UART Release the object |
| uart_discard_transmit | Discard transmission |
| uart_discard_receive | Discard reception |
| uart_transmitlt | Send data. Non-blocking communication |
| uart_receivevt | Receive data. Non-blocking communication |
| uart_transmit_irq_handler | IRQ handler for transfer |
| uart_receive_irq_handler | IRQ handler for receiving |
| uart_error_irq_handler | IRQ handler for errors |
| uart_get_status | Get status |
| uart_get_error | Get error |
| uart_get_boudrate_setting | Get boudrate settings |
| uart_dma_init | UART DMA Object initialization |
| uart_dma_deinit | UART DMA Release the object |
| uart_dma_discard_transmit | Discard transmission |
| uart_dma_discard_receive | Discard reception |
| uart_dma_transmitlt | Send data. Non-blocking communication |
| uart_dma_receivevt | Receive data. Non-blocking communication |
| uart_send_break | Send a break |
| uart_stop_break | Stop break |
| uart_enable_half_clock | Half clock mode enabled |
| uart_disable_half_clock | Half clock mode disabled |
| uart_enable_loopback | Enable loopback |
| uart_disable_loopback | Disable loopback |
| uart_enable_wakeup | Enable wake-up |
| uart_disable_wakeup | Disable wake-up |

8. Revision History

| Revision | Date | Description |
|----------|------------|---------------|
| 1.0 | 2023-06-28 | First release |

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